

Colony Scout - Issues

#	Tracker	Status	Priority	Subject	Assignee	Updated	Category	% Done
844	Task	Wontfix	High	Bootloader	Brad Neuman	09/21/2010 09:13 PM	OS	0
1097	Task	Fixed	Normal	Email Steve about bootstrapping ARM	Kevin Woo	02/10/2010 04:17 PM	OS	100
1098	Task	Wontfix	Urgent	ask aaron and cornell about arm stuff	Brad Neuman	09/21/2010 09:13 PM	OS	0
1587	Task	Assigned	Normal	NanoRK Wireless Library	Dan Jacobs	10/09/2011 03:09 PM	OS	0
1588	Task	Assigned	Normal	Look @ Robostix AVR<->ARM Comms Implementation	Ben Wasserman	11/18/2010 03:13 AM	OS	0
1725	Task	Fixed	Normal	Get ROS on Gumstix	Jeff Cooper	10/17/2011 05:44 PM	OS	90
1817	Task	Assigned	Normal	Create ROS Node: Buttons	Priyanka Deo	11/14/2011 02:28 PM	OS	100
1818	Task	Assigned	Normal	Create ROS Node: Timer	Alexander Lam	11/09/2011 06:53 PM	OS	100
1819	Task	Fixed	Normal	Create ROS Node: Headlights	Ben Wasserman	11/16/2011 08:15 PM	OS	100
1820	Task	Fixed	Normal	Create ROS Node: Power	Jeff Cooper	11/11/2011 02:16 AM	OS	100
1821	Task	Assigned	Normal	Create ROS Node: IMU	Dan Jacobs	10/23/2011 02:42 AM	OS	0
1822	Task	Assigned	Normal	Create ROS Node: Accessory	Willis Chang	11/14/2011 12:11 AM	OS	100
1823	Task	Assigned	Normal	Create ROS Node: Encoders	Lalitha Ganesan	11/02/2011 06:41 PM	OS	100
1824	Task	Fixed	Normal	Create ROS Node: Sonar	Alex Zirbel	10/26/2011 05:37 PM	OS	0
1825	Task	Assigned	Normal	Create ROS Node: Wireless	Prashant Sridhar	10/23/2011 02:42 AM	OS	0
1826	Task	Assigned	Normal	Create ROS Node: USB Serial	Lalitha Ganesan	10/26/2011 07:26 PM	OS	80
1827	Task	Fixed	Low	Create ROS Node: AVR Bridge	Thomas Mullins	04/03/2012 04:16 PM	OS	100
1828	Task	Assigned	Normal	Create ROS Node: Cliffsensors	Priyanka Deo	11/14/2011 02:27 PM	OS	100
1829	Task	Assigned	Normal	Create ROS Node: BOM	James Carroll	11/09/2011 10:06 PM	OS	90
1830	Task	Assigned	Normal	Create ROS Node: Analog	Devendra Gurjar	10/23/2011 02:42 AM	OS	0
1850	Task	Assigned	Normal	BOM Driver Code	Dan Jacobs	10/26/2011 05:53 PM	OS	0
1853	Task	Assigned	Normal	Sonar Position Tracking	Prasanth Somasundar	10/26/2011 06:10 PM	OS	0
1854	Task	Assigned	Normal	Send Sonar Readings to ARM	Prasanth Somasundar	10/26/2011 06:10 PM	OS	0
1855	Task	Assigned	Normal	Automate Stepping and Sonar Reading	Prasanth Somasundar	10/26/2011 06:11 PM	OS	0
1856	Task	Assigned	Normal	Sonar on ARM	Prasanth Somasundar	10/26/2011 06:11 PM	OS	0
1857	Task	Assigned	Normal	Make ARM command Sonar on AVR	Prasanth Somasundar	10/26/2011 06:12 PM	OS	0
1858	Task	Assigned	Normal	Read IMU values and send to ARM	Yuyang Guo	10/26/2011 06:07 PM	OS	0
1860	Task	Assigned	Normal	Pose Estimation	Yuyang Guo	10/26/2011 06:08 PM	OS	0
1862	Task	Assigned	Normal	Control Motors (ARM)	Alexander Lam	11/16/2011 06:33 PM	OS	10
1863	Task	Assigned	Normal	Track Encoders	Alexander Lam	10/26/2011 06:04 PM	OS	0
1864	Task	Assigned	Normal	"Automated" Turning	Alexander Lam	10/26/2011 06:06 PM	OS	0

#	Tracker	Status	Priority	Subject	Assignee	Updated	Category	% Done
1872	Task	Assigned	Normal	IMU on ARM	Yuyang Guo	10/26/2011 06:08 PM	OS	0
1873	Task	Assigned	Normal	ROSSERIAL on ARM	Jonathan Goldman	11/11/2011 07:09 PM	OS	0
1874	Task	Assigned	Normal	Test AVR on ARM	Jonathan Goldman	10/26/2011 06:06 PM	OS	0
1875	Task	Assigned	Normal	CliffSensor on ARM	Lalitha Ganesan	10/26/2011 06:07 PM	OS	0
1876	Task	Assigned	Normal	Create Transmitting Protocol	Ben Wasserman	10/26/2011 05:49 PM	OS	0
1877	Task	Assigned	Normal	Wireless on ARM	Ben Wasserman	11/07/2011 06:05 PM	OS	10
1878	Bug	Assigned	Normal	Cliff Detection	Lalitha Ganesan	10/26/2011 06:07 PM	OS	0
1879	Task	Assigned	Normal	Buttons on ARM	Priyanka Deo	10/26/2011 06:07 PM	OS	0
1892	Bug	Fixed	Normal	Create Alarm Clocks	Alexander Lam	12/01/2011 04:50 PM	OS	100
1893	Task	Wontfix	Tabled	Power ROS Node	Jeff Cooper	04/12/2013 05:45 PM	OS	70
1894	Task	Assigned	Normal	USB Serial on ARM	Ben Wasserman	10/29/2011 05:51 PM	OS	0
1895	Task	New	Normal	Control Headlights		10/29/2011 05:52 PM	OS	0
2135	Task	Fixed	Normal	Remove headers from messages	Hui Jun Tay	02/28/2013 12:12 PM	OS	0
2137	Task	Wontfix	Normal	Add roslaunch scripts	Priyanka Deo	02/28/2013 12:15 PM	OS	0