

Colony

	2012-12				2013-1					2013-2					2013-3					2013-4					2013-5				
	49	50	51	52	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21				
Colony	Colony																												
Battery Level Indicator																													
Improve library error codes																													
Better sanity check for invalid BOM type																													
XBee/Wireless Initialization																													
get all the library inti's and functions (...)																													
Xbee Documentation																													
xbee baud rates																													
Wireless - core send, ack functions																													
Wireless - xbee.c																													
xbee id																													
investigate new AVR simulator?																													
Conclusion on filter design	Assigned 0%																												
Figure out rangefinders group	Assigned 0%																												
Complete SURG form	Assigned 0%																												
Check/Order robot battery clips	Assigned 50%																												
Line Follower Collimator																													
Redo robot pants																													
Get Colony videos onto VideoTron. Embed in (...)																													
Clean up repository branches																													
Add Line Following to Library																													
Profile different mapping surfaces																													
Make Hunter-Prey Ref More Verbose																													
Clean up Colony-New and prepare for next (...)																													
Implement Intersection Behavior																													
wl_basic_do_default(int *length) doesn't (...)																													
Schedule Fleet Maintenance Day																													
Discuss and Contact about Extra Colony III (...)																													

Colony - Hardware

Design Dragonfly Replacement Board

Investigate how to use the JTAG ICE

Colony - Library

Make sure all robots program the correct (...)

Colony - Reliability

Automatically update robot status page (...)