Colony

| | 2017-9 | | | | | 201 | 7-10 | | | 2017-11 | | | | 2017-12 | | | | | 201 | 8-1 | | | 2 | 018- | 2 |
|---|--------|------|-------|----|----|-----|------|----|----|---------|----|----|----|---------|----|----|----|---|-----|-----|---|---|---|------|---|
| | 36 | | 38 | 39 | 40 | 41 | 42 | 43 | 44 | 45 | 46 | 47 | 48 | 49 | 50 | 51 | 52 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| Colony | Co | lony | | | | | | | | | | | | | | | | | | | | | | | |
| Battery Level Indicator | | | | | | | | | | | | | | | | | | | | | | | | | |
| Improve library error codes | | | | | | | | | | | | | | | | | | | | | | | | | |
| Better sanity check for invalid BOM type | | | | | | | | | | | | | | | | | | | | | | | | | |
| XBee/Wireless Initialization | | | | | | | | | | | | | | | | | | | | | | | | | |
| get all the library inti's and functions () | | | | | | | | | | | | | | | | | | | | | | | | | |
| Xbee Documentation | | | | | | | | | | | | | | | | | | | | | | | | | |
| xbee baud rates | | | | | | | | | | | | | | | | | | | | | | | | | |
| Wireless - core send, ack functions | | | | | | | | | | | | | | | | | | | | | | | | | |
| Wireless - xbee.c | | | | | | | | | | | | | | | | | | | | | | | | | |
| xbee id | | | | | | | | | | | | | | | | | | | | | | | | | |
| investigate new AVR simulator? | | | | | | | | | | | | | | | | | | | | | | | | | |
| Conclusion on filter design | | _ | ed 0° | | | | | | | | | | | | | | | | | | | | | | |
| Figure out rangefinders group | | _ | ed 0° | | | | | | | | | | | | | | | | | | | | | | |
| Complete SURG form | | _ | ed 0° | | | | | | | | | | | | | | | | | | | | | | |
| Check/Order robot battery clips | As | sign | ed 50 |)% | | | | | | | | | | | | | | | | | | | | | |
| Line Follower Collimator | | | | | | | | | | | | | | | | | | | | | | | | | |
| Redo robot pants | | | | | | | | | | | | | | | | | | | | | | | | | |
| Get Colony videos onto VideoTron. Embed in () | | | | | | | | | | | | | | | | | | | | | | | | | |
| Clean up repository branches | | | | | | | | | | | | | | | | | | | | | | | | | |
| Add Line Following to Library | | | | | | | | | | | | | | | | | | | | | | | | | |
| Profile different mapping surfaces | | | | | | | | | | | | | | | | | | | | | | | | | |
| Make Hunter-Prey Ref More Verbose | | | | | | | | | | | | | | | | | | | | | | | | | |
| Clean up Colony-New and prepare for next () | | | | | | | | | | | | | | | | | | | | | | | | | |
| Implement Intersection Behavior | | | | | | | | | | | | | | | | | | | | | | | | | |
| wl_basic_do_default(int *length) doesn't () | | | | | | | | | | | | | | | | | | | | | | | | | |
| Schedule Fleet Maintenence Day | | | | | | | | | | | | | | | | | | | | | | | | | |
| Discuss and Contact about Extra Colony III () | | | | | | | | | | | | | | | | | | | | | | | | | |

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| | Colony - Hardware |
|---|---|
| | Design Dragonfly Replacement Board |
| | Investigate how to use the JTAG ICE |
| | Colony - Library |
| | Make sure all robots program the correct () |
| | Colony - Reliability |
| İ | Automatically update robot status page () |

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