Colony

		201	9-8	3			20)19-9				20	19-1	0			201	9-1	1			20	19-1	2			20	20-1		_
	32			34	35	36	37	⁷ 38	3	9 4	40	41	42	43	44	45	4	6	47	48	49	50	51	52	1	2	2	3	4	
Colony	C	olon	y																											
Battery Level Indicator																														
Improve library error codes																														
Better sanity check for invalid BOM type																														
XBee/Wireless Initialization																														
get all the library inti's and functions ()																														
Xbee Documentation																														
xbee baud rates																														
Wireless - core send, ack functions																														
Wireless - xbee.c																														
xbee id																														
investigate new AVR simulator?																														
Conclusion on filter design		_		10%																										
Figure out rangefinders group		_		10%																										
Complete SURG form		_		10%																										
Check/Order robot battery clips	A	ssigi	ned	1 50%	0																									
Line Follower Collimator																														
Redo robot pants																														
Get Colony videos onto VideoTron. Embed in ()																														
Clean up repository branches																														
Add Line Following to Library																														
Profile different mapping surfaces																														
Make Hunter-Prey Ref More Verbose																														
Clean up Colony-New and prepare for next ()																														
Implement Intersection Behavior																														
wl_basic_do_default(int *length) doesn't ()																														
Schedule Fleet Maintenence Day																														
Discuss and Contact about Extra Colony III ()																														

04/19/2024

Colony - Hardware	
Design Dragonfly Replacement Board	
Investigate how to use the JTAG ICE	
Colony - Library	
Make sure all robots program the correct ()	
Colony - Reliability	
Automatically update robot status page ()	

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