## Colony

			201	3-8	8				201	3-9				20	13-1	10			2	2013	-11				201	3-12				2014	-1	
		32			34	35	3	6	37	38	39	) 4	0	41	42	43	4	4	45	46	47	' 48	3 4	49	50	51	52	1	2	3	4	,
Colony		С	olon	y																												
Battery Level Indicator																																
Improve library error codes																																
Better sanity check for invalid BOM type																																
XBee/Wireless Initialization																																
get all the library inti's and functions ()																																
Xbee Documentation																																
xbee baud rates																																
Wireless - core send, ack functions																																
Wireless - xbee.c																																
xbee id																																
investigate new AVR simulator?																																
Conclusion on filter design			ssig																													
Figure out rangefinders group			ssig																													
Complete SURG form			ssig																													
Check/Order robot battery clips		A	ssig	neo	d 50	0%																										
Line Follower Collimator																																
Redo robot pants																																
Get Colony videos onto VideoTron. Embed in ()																																
Clean up repository branches																																
Add Line Following to Library																																
Profile different mapping surfaces																																
Make Hunter-Prey Ref More Verbose																																
Clean up Colony-New and prepare for next ()																																
Implement Intersection Behavior																																
wl_basic_do_default(int *length) doesn't ()																																
Schedule Fleet Maintenence Day																																
Discuss and Contact about Extra Colony III ()	1																															

Colony - Hardware
Design Dragonfly Replacement Board
Investigate how to use the JTAG ICE
Colony - Library
Make sure all robots program the correct ()
Colony - Reliability
Automatically update robot status page ()