Colony

| | | 2018 | 8-6 | | | 20 | 18-7 | | | | 2018 | -8 | | | 201 | 8-9 | | | 20 | 18-10 |) | | | 2018 | -11 | |
|---|----|-------|--------|----|----|----|------|----|----|----|------|----|----|----|-----|-----|----|----|----|-------|----|----|----|------|-----|--|
| | 23 | | | 26 | 27 | 28 | 29 | 30 | 31 | 32 | 2 33 | 34 | 35 | 36 | 37 | 38 | 39 | 40 | 41 | 42 | 43 | 44 | 45 | 46 | 47 | |
| Colony | C | olony | y | | | | • | | | | | • | • | • | | • | • | • | | • | | • | • | • | • | |
| Battery Level Indicator | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Improve library error codes | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Better sanity check for invalid BOM type | | | | | | | | | | | | | | | | | | | | | | | | | | |
| XBee/Wireless Initialization | | | | | | | | | | | | | | | | | | | | | | | | | | |
| get all the library inti's and functions () | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Xbee Documentation | | | | | | | | | | | | | | | | | | | | | | | | | | |
| xbee baud rates | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Wireless - core send, ack functions | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Wireless - xbee.c | | | | | | | | | | | | | | | | | | | | | | | | | | |
| xbee id | | | | | | | | | | | | | | | | | | | | | | | | | | |
| investigate new AVR simulator? | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Conclusion on filter design | | _ | ned 0% | | | | | | | | | | | | | | | | | | | | | | | |
| Figure out rangefinders group | | _ | ned 0% | | | | | | | | | | | | | | | | | | | | | | | |
| Complete SURG form | | _ | ned 0% | | | | | | | | | | | | | | | | | | | | | | | |
| Check/Order robot battery clips | A | ssigr | ned 50 | % | | | | | | | | | | | | | | | | | | | | | | |
| Line Follower Collimator | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Redo robot pants | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Get Colony videos onto VideoTron. Embed in () | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Clean up repository branches | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Add Line Following to Library | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Profile different mapping surfaces | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Make Hunter-Prey Ref More Verbose | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Clean up Colony-New and prepare for next () | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Implement Intersection Behavior | | | | | | | | | | | | | | | | | | | | | | | | | | |
| wl_basic_do_default(int *length) doesn't () | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Schedule Fleet Maintenence Day | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Discuss and Contact about Extra Colony III () | | | | | | | | | | | | | | | | | | | | | | | | | | |

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| Colony - Hardware |
|---|
| Design Dragonfly Replacement Board |
| Investigate how to use the JTAG ICE |
| Colony - Library |
| Make sure all robots program the correct () |
| Colony - Reliability |
| Automatically update robot status page () |

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