

Colony

| | 2013-5 | | | | 2013-6 | | | | 2013-7 | | | | 2013-8 | | | | 2013-9 | | | | 2013-10 | | | |
|--|---------------|----|----|----|--------|----|----|----|--------|----|----|----|--------|----|----|----|--------|----|----|----|---------|----|----|----|
| | 19 | 20 | 21 | 22 | 23 | 24 | 25 | 26 | 27 | 28 | 29 | 30 | 31 | 32 | 33 | 34 | 35 | 36 | 37 | 38 | 39 | 40 | 41 | 42 |
| Colony | Colony | | | | | | | | | | | | | | | | | | | | | | | |
| Battery Level Indicator | | | | | | | | | | | | | | | | | | | | | | | | |
| Improve library error codes | | | | | | | | | | | | | | | | | | | | | | | | |
| Better sanity check for invalid BOM type | | | | | | | | | | | | | | | | | | | | | | | | |
| XBee/Wireless Initialization | | | | | | | | | | | | | | | | | | | | | | | | |
| get all the library inti's and functions (...) | | | | | | | | | | | | | | | | | | | | | | | | |
| Xbee Documentation | | | | | | | | | | | | | | | | | | | | | | | | |
| xbee baud rates | | | | | | | | | | | | | | | | | | | | | | | | |
| Wireless - core send, ack functions | | | | | | | | | | | | | | | | | | | | | | | | |
| Wireless - xbee.c | | | | | | | | | | | | | | | | | | | | | | | | |
| xbee id | | | | | | | | | | | | | | | | | | | | | | | | |
| investigate new AVR simulator? | | | | | | | | | | | | | | | | | | | | | | | | |
| Conclusion on filter design | Assigned 0% | | | | | | | | | | | | | | | | | | | | | | | |
| Figure out rangefinders group | Assigned 0% | | | | | | | | | | | | | | | | | | | | | | | |
| Complete SURG form | Assigned 0% | | | | | | | | | | | | | | | | | | | | | | | |
| Check/Order robot battery clips | Assigned 50% | | | | | | | | | | | | | | | | | | | | | | | |
| Line Follower Collimator | | | | | | | | | | | | | | | | | | | | | | | | |
| Redo robot pants | | | | | | | | | | | | | | | | | | | | | | | | |
| Get Colony videos onto VideoTron. Embed in (...) | | | | | | | | | | | | | | | | | | | | | | | | |
| Clean up repository branches | | | | | | | | | | | | | | | | | | | | | | | | |
| Add Line Following to Library | | | | | | | | | | | | | | | | | | | | | | | | |
| Profile different mapping surfaces | | | | | | | | | | | | | | | | | | | | | | | | |
| Make Hunter-Prey Ref More Verbose | | | | | | | | | | | | | | | | | | | | | | | | |
| Clean up Colony-New and prepare for next (...) | | | | | | | | | | | | | | | | | | | | | | | | |
| Implement Intersection Behavior | | | | | | | | | | | | | | | | | | | | | | | | |
| wl_basic_do_default(int *length) doesn't (...) | | | | | | | | | | | | | | | | | | | | | | | | |
| Schedule Fleet Maintenance Day | | | | | | | | | | | | | | | | | | | | | | | | |
| Discuss and Contact about Extra Colony III (...) | | | | | | | | | | | | | | | | | | | | | | | | |

Colony - Hardware

Design Dragonfly Replacement Board

Investigate how to use the JTAG ICE

Colony - Library

Make sure all robots program the correct (...)

Colony - Reliability

Automatically update robot status page (...)