

# Colony

|  | 2014-2        |   |   |   | 2014-3 |    |    |    | 2014-4 |    |    |    | 2014-5 |    |    |    | 2014-6 |    |    |    | 2014-7 |    |    |    |
|--|---------------|---|---|---|--------|----|----|----|--------|----|----|----|--------|----|----|----|--------|----|----|----|--------|----|----|----|
|  | 6             | 7 | 8 | 9 | 10     | 11 | 12 | 13 | 14     | 15 | 16 | 17 | 18     | 19 | 20 | 21 | 22     | 23 | 24 | 25 | 26     | 27 | 28 | 29 |
| <b>Colony</b>                                    | <b>Colony</b> |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Battery Level Indicator                          |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Improve library error codes                      |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Better sanity check for invalid BOM type         |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| XBee/Wireless Initialization                     |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| get all the library inti's and functions (...)   |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Xbee Documentation                               |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| xbee baud rates                                  |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Wireless - core send, ack functions              |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Wireless - xbee.c                                |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| xbee id  |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Conclusion on filter design                      | Assigned 0%   |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Figure out rangefinders group                    | Assigned 0%   |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Complete SURG form                               | Assigned 0%   |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Check/Order robot battery clips                  | Assigned 50%  |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Line Follower Collimator                         |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Redo robot pants                                 |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Get Colony videos onto VideoTron. Embed in (...) |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Clean up repository branches                     |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Add Line Following to Library                    |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Profile different mapping surfaces               |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Make Hunter-Prey Ref More Verbose                |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Clean up Colony-New and prepare for next (...)   |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Implement Intersection Behavior                  |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| wl_basic_do_default(int *length) doesn't (...)   |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Schedule Fleet Maintenance Day                   |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Discuss and Contact about Extra Colony III (...) |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |
| Colony - Hardware                                |               |   |   |   |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |        |    |    |    |

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| <b>Investigate how to use the JTAG ICE</b><br><b>Colony - Library</b><br><b>Make sure all robots program the correct (...)</b> |  |
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