Colony

	2014-10					2014-11					2014-12					2015-1						2015-2					2015-3			
	41			4	4 4	5	46	47	48	49	50	51	52	2	1	2	3	4	5		6	7	8	9	10	11	12	13		
Colony	Co	lony								•	•	•		•	•			•	•									•		
Battery Level Indicator																														
Improve library error codes																														
Better sanity check for invalid BOM type																														
XBee/Wireless Initialization																														
get all the library inti's and functions ()																														
Xbee Documentation																														
xbee baud rates																														
Wireless - core send, ack functions																														
Wireless - xbee.c																														
xbee id																														
investigate new AVR simulator?																														
Conclusion on filter design		-	ed 0%																											
Figure out rangefinders group		-	ed 0%																											
Complete SURG form		-	ed 0%																											
Check/Order robot battery clips	As	sign	ed 50	%																										
Line Follower Collimator																														
Redo robot pants																														
Get Colony videos onto VideoTron. Embed in ()																														
Clean up repository branches																														
Add Line Following to Library																														
Profile different mapping surfaces																														
Make Hunter-Prey Ref More Verbose																														
Clean up Colony-New and prepare for next ()																														
Implement Intersection Behavior																														
wl_basic_do_default(int *length) doesn't ()																														
Schedule Fleet Maintenence Day																														
Discuss and Contact about Extra Colony III ()																														

Colony - Hardware
Design Dragonfly Replacement Board
Investigate how to use the JTAG ICE
Colony - Library
Make sure all robots program the correct ()
Colony - Reliability
Automatically update robot status page ()