

Colony - Issues

| # | Tracker | Status | Priority | Subject | Assignee | Updated | Category | % Done |
|------|-------------|----------|----------|--|---------------|---------------------|--------------------|--------|
| 1568 | Task | Assigned | Tabled | Clean up Colony-New and prepare for next year | John Sexton | 11/08/2010 10:48 PM | Administration | 0 |
| 1400 | Task | Assigned | Low | Complete SURG form | John Sexton | 09/07/2010 05:49 PM | Administration | 0 |
| 1466 | Task | Assigned | Low | Clean up repository branches | John Sexton | 10/10/2010 12:38 AM | Administration | 10 |
| 1903 | Enhancement | Assigned | Normal | Discuss and Contact about Extra Colony III Boards | Priyanka Deo | 11/16/2011 08:24 PM | Administration | 50 |
| 1576 | Task | Assigned | Normal | Schedule Fleet Maintenance Day | Ben Wasserman | 11/18/2010 09:03 PM | Administration | 50 |
| 1464 | Task | Assigned | Normal | Get Colony videos onto VideoTron. Embed in website. | Nico Paris | 01/17/2011 03:42 PM | Administration | 80 |
| 320 | Enhancement | New | Tabled | Automatically update robot status page with testing station | | 03/21/2009 12:55 PM | Diagnostic Station | 0 |
| 1458 | Task | Assigned | Tabled | Redo robot pants | Austin Buchan | 10/01/2010 05:40 PM | Hardware | 0 |
| 1453 | Task | Assigned | Tabled | Line Follower Collimator | Megan Dority | 10/12/2010 07:56 PM | Hardware | 0 |
| 1389 | Task | Assigned | Normal | Figure out rangefinders group | John Sexton | 09/03/2010 11:39 PM | Hardware | 0 |
| 1387 | Task | Assigned | Normal | Conclusion on filter design | John Sexton | 09/03/2010 11:39 PM | Hardware | 0 |
| 693 | Bug | Assigned | Tabled | Better sanity check for invalid BOM type | John Sexton | 10/01/2010 05:45 PM | Hardware | 0 |
| 390 | Task | Feedback | Tabled | Investigate how to use the JTAG ICE | Nico Paris | 09/24/2009 11:08 AM | Hardware | 0 |
| 237 | Enhancement | Feedback | Tabled | Design Dragonfly Replacement Board | | 03/21/2009 12:54 PM | Hardware | 0 |
| 1439 | Task | Assigned | Normal | Check/Order robot battery clips | Nico Paris | 11/17/2010 03:41 PM | Hardware | 50 |
| 1562 | Task | Assigned | Low | Make Hunter-Prey Ref More Verbose | Ben Wasserman | 11/12/2010 05:11 PM | Introductory Labs | 0 |
| 577 | Enhancement | Assigned | Tabled | Improve library error codes | Brad Neuman | 09/30/2010 08:25 PM | Library | 0 |
| 575 | Bug | Assigned | Tabled | Battery Level Indicator | John Sexton | 09/30/2010 08:00 PM | Library | 0 |
| 368 | Task | Assigned | Tabled | Make sure all robots program the correct xbee id from eeprom | Brian Coltin | 10/02/2010 07:24 PM | Library | 0 |
| 798 | Enhancement | Assigned | Normal | get all the library inti's and functions to behave | Brad Neuman | 10/02/2010 07:13 PM | Library | 30 |
| 964 | Task | Feedback | Tabled | investigate new AVR simulator? | | 12/18/2009 07:30 AM | Simulator | 0 |
| 1574 | Bug | Assigned | Normal | wl_basic_do_default(int *length) doesn't set *length to zero if no packet received | Ben Wasserman | 11/11/2010 09:37 PM | Traffic Navigation | 0 |
| 1570 | Task | Assigned | Normal | Implement Intersection Behavior | Ben Wasserman | 11/19/2010 04:57 PM | Traffic Navigation | 30 |
| 1534 | Task | Assigned | High | Add Line Following to Library | Ben Wasserman | 11/16/2010 12:55 AM | Traffic Navigation | 70 |
| 1556 | Task | Assigned | Normal | Profile different mapping surfaces | Willis Chang | 12/03/2010 05:01 PM | Traffic Navigation | 90 |
| 960 | Bug | Assigned | Low | xbee id | Ben Wasserman | 09/30/2010 09:26 PM | Wireless | 0 |
| 852 | Bug | Assigned | Low | Xbee Documentation | Priyanka Deo | 11/09/2011 12:17 AM | Wireless | 0 |
| 790 | Bug | Assigned | Normal | XBee/Wireless Initialization | Brad Neuman | 10/02/2010 07:16 PM | Wireless | 0 |
| 950 | Task | Assigned | Low | Wireless - xbee.c | Ben Wasserman | 10/02/2010 07:18 PM | Wireless | 80 |
| 946 | Task | Assigned | Low | Wireless - core send, ack functions | Ben Wasserman | 10/02/2010 07:17 PM | Wireless | 90 |
| 925 | Enhancement | Assigned | Low | xbee baud rates | Ben Wasserman | 09/30/2010 09:27 PM | Wireless | 90 |