

Colony - Issues

| # | Tracker | Status | Priority | Subject | Assignee | Updated | Category | % Done |
|-----|-------------|------------|----------|---|-------------|---------------------|-----------------------|--------|
| 576 | Enhancement | Wontfix | Low | BOM calibration | Brad Neuman | 09/25/2010 03:11 PM | | 0 |
| 569 | Task | Invalid | Normal | comment eeprom.c | Brad Neuman | 09/30/2010 08:24 PM | Library | 0 |
| 562 | Bug | Duplicate | Tabled | Fix init functions | Brad Neuman | 10/02/2010 07:15 PM | Library | 0 |
| 446 | Task | Wontfix | Normal | Implement the BOM in the Simulator | Brad Neuman | 09/30/2010 08:17 PM | Simulator | 0 |
| 391 | Task | Wontfix | Normal | Investigate and profile the avr-libc floating point emulation | Brad Neuman | 09/25/2010 03:18 PM | Library | 0 |
| 367 | Enhancement | Fixed | Normal | Prevent loading of non robot code into the simulator | Brad Neuman | 04/10/2009 05:13 PM | Simulator | 0 |
| 347 | Enhancement | Fixed | High | Deal with speed issues | Brad Neuman | 03/21/2009 12:51 PM | Simulator | 0 |
| 339 | Task | Fixed | Normal | Clean up memory for multiple robots in simulator | Brad Neuman | 04/03/2009 05:09 PM | Simulator | 0 |
| 333 | Task | Fixed | High | Simulate Multiple Robots | Brad Neuman | 03/21/2009 12:51 PM | Simulator | 0 |
| 331 | Enhancement | Fixed | Normal | Cleanup on Closure | Brad Neuman | 03/21/2009 12:51 PM | Simulator | 0 |
| 329 | Task | Fixed | High | Program all robot's EEPROMs | Brad Neuman | 03/21/2009 12:49 PM | Hardware | 0 |
| 325 | Task | Fixed | High | Control Robot Processes | Brad Neuman | 03/21/2009 12:51 PM | Simulator | 0 |
| 314 | Task | Worksforme | High | Send Charging Board Documents to Kevin | Brad Neuman | 03/21/2009 12:48 PM | Autonomous Recharging | 0 |
| 304 | Enhancement | Invalid | Low | Rangefinders code distance comments | Brad Neuman | 03/21/2009 12:50 PM | Library | 0 |
| 300 | Bug | Fixed | High | SPI failure | Brad Neuman | 03/21/2009 12:50 PM | Library | 0 |
| 274 | Task | Fixed | Low | Unit Test Architecture | Brad Neuman | 03/21/2009 12:51 PM | | 0 |
| 271 | Task | Wontfix | Low | design wireless packet for use with manipulation | Brad Neuman | 03/21/2009 12:50 PM | | 0 |
| 270 | Enhancement | Wontfix | Low | adapt orbit and BFS for cooperative manipulation | Brad Neuman | 03/21/2009 12:50 PM | | 0 |
| 231 | Bug | Fixed | Low | Resolve ARCHS inductor problem | Brad Neuman | 03/21/2009 12:48 PM | Autonomous Recharging | 0 |
| 183 | Task | Fixed | Normal | Write Encoder Library | Brad Neuman | 03/21/2009 12:49 PM | Hardware | 0 |
| 181 | Task | Wontfix | Low | Design object recognition system | Brad Neuman | 03/21/2009 12:50 PM | | 0 |
| 173 | Task | Invalid | Low | Design manipulators | Brad Neuman | 03/21/2009 12:50 PM | | 0 |