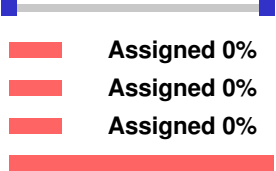


|  | 2012-11       |    |    |    | 2012-12 |    |    |    | 2013-1 |   |   |   |   | 2013-2 |   |   |   | 2013-3 |    |    |    | 2013-4 |    |    |    |
|--|---------------|----|----|----|---------|----|----|----|--------|---|---|---|---|--------|---|---|---|--------|----|----|----|--------|----|----|----|
|  | 45            | 46 | 47 | 48 | 49      | 50 | 51 | 52 | 1      | 2 | 3 | 4 | 5 | 6      | 7 | 8 | 9 | 10     | 11 | 12 | 13 | 14     | 15 | 16 | 17 |
| <b>Colony</b>                                    | <b>Colony</b> |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Battery Level Indicator                          |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Improve library error codes                      |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Better sanity check for invalid BOM type         |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| XBee/Wireless Initialization                     |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| get all the library inti's and functions (...)   |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Xbee Documentation                               |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| xbee baud rates                                  |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Wireless - core send, ack functions              |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Wireless - xbee.c                                |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| xbee id  |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| investigate new AVR simulator?                   |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Conclusion on filter design                      | Assigned 0%   |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Figure out rangefinders group                    | Assigned 0%   |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Complete SURG form                               | Assigned 0%   |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Check/Order robot battery clips                  | Assigned 50%  |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Line Follower Collimator                         |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Redo robot pants                                 |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Get Colony videos onto VideoTron. Embed in (...) |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Clean up repository branches                     |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Add Line Following to Library                    |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Profile different mapping surfaces               |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Make Hunter-Prey Ref More Verbose                |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Clean up Colony-New and prepare for next (...)   |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Implement Intersection Behavior                  |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| wl_basic_do_default(int *length) doesn't (...)   |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Schedule Fleet Maintenance Day                   |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |
| Discuss and Contact about Extra Colony III (...) |               |    |    |    |         |    |    |    |        |   |   |   |   |        |   |   |   |        |    |    |    |        |    |    |    |

|  |  |
|--|--|
| <p><b>Colony - Hardware</b><br/> Design Dragonfly Replacement Board<br/> Investigate how to use the JTAG ICE</p> <p><b>Colony - Library</b><br/> Make sure all robots program the correct (...)</p> <p><b>Colony - Reliability</b><br/> Automatically update robot status page (...)</p> <p><b>Colony Scout</b><br/> Colony Environment<br/> Software Architecture<br/> Reflow Oven Temperature Regulation<br/> Update Boards on Eagle<br/> Research PCB Assembly Costing<br/> Website Work Log<br/> Video for Scout Intro<br/> Create ROS Node: Buttons<br/> Create ROS Node: Timer<br/> Create ROS Node: IMU<br/> Create ROS Node: Accessory<br/> Create ROS Node: Encoders<br/> Create ROS Node: Wireless<br/> Create ROS Node: USB Serial<br/> Create ROS Node: Cliffsensors<br/> Create ROS Node: BOM<br/> Create ROS Node: Analog<br/> BOM Interference Testing<br/> BOM Driver Code<br/> Sonar Wiring<br/> Sonar Position Tracking<br/> Send Sonar Readings to ARM<br/> Automate Stepping and Sonar Reading<br/> Sonar on ARM<br/> Make ARM command Sonar on AVR<br/> Read IMU values and send to ARM</p> | <p><b>Colony Scout</b></p> <p><b>Assigned 100%</b><br/> <b>Assigned 100%</b><br/> <b>Assigned 0%</b><br/> <b>Assigned 100%</b><br/> <b>Assigned 100%</b><br/> <b>Assigned 0%</b><br/> <b>Assigned 80%</b><br/> <b>Assigned 100%</b><br/> <b>Assigned 90%</b><br/> <b>Assigned 0%</b><br/> <b>Assigned 0%</b><br/> <b>Assigned 0%</b><br/> <b>Assigned 0%</b></p> <p><b>Assigned 0%</b></p> |
|--|--|

|   |              |
|---|--------------|
| Pose Estimation                             | Assigned 0%  |
| Motor & Encoder Wiring                      |              |
| Control Motors (ARM)                        | Assigned 10% |
| Track Encoders                              |              |
| Charging Base                               |              |
| Print and Test Scoutfly                     |              |
| Create Scout Chassis                        |              |
| Make wiring kits for Scout                  |              |
| IMU on ARM                                  | Assigned 0%  |
| ROSSERIAL on ARM                            | Assigned 0%  |
| CliffSensor on ARM                          | Assigned 0%  |
| Create Transmitting Protocol                | Assigned 0%  |
| Wireless on ARM                             | Assigned 10% |
| Cliff Detection                             | Assigned 0%  |
| Buttons on ARM                              | Assigned 0%  |
| USB Serial on ARM                           | Assigned 0%  |
| Control Headlights                          |              |
| Power Up Rest of Scoutfly                   |              |
| Get Old Boards and Funding Info             |              |
| Test AVR on ARM                             | Assigned 0%  |
| Get Sonar Stepping and Reading              | Assigned 0%  |
| "Automated" Turning                         | Assigned 0%  |
| Add Fuel Guage and Protection circuit (...) |              |
| BOM returns values even when IR LED (...)   |              |
| File Error Service call                     |              |
| Colony Scout - 1.0                          |              |
| BOM Send/Receive Functions                  |              |
| Assembly Instructions                       |              |
| Fix Encoder pinout on breakfly              |              |
| Colony Scout - 1.2                          |              |
| NanoRK Wireless Library                     |              |
| Look @ Robostix AVR<->ARM Comms (...)       |              |
| Electronics Purchasing, OCT-08              | Assigned 0%  |
| Colony Scout - Development                  |              |

|  |   |   |
|--|---|---|
| <p><b>System Wiring</b><br/>         Look into accelerometer speed<br/>         Email Red W<br/>         Create roboclub demo<br/>         Audio Command &amp; Output Accessory<br/>         Design SmartFly Smart Accessory (...)<br/>         Mechanical Work Log<br/>         Check speaker magnet interference (...)</p> | <p><b>Assigned 0%</b><br/> <b>Assigned 50%</b></p>    |   |
| <p><b>HyLo</b><br/>         type proposed proposal<br/>         Meeting</p>  | <p><b>HyLo</b><br/> <b>Assigned 0%</b></p>            |   |
| <p><b>Mechanical Logic Gates</b><br/>         Update - website<br/>         You Tube + Display Case<br/>         Website - host on roboclub<br/>         Look into getting copywrite</p>   |   |  <p><b>Assigned 0%</b><br/> <b>Assigned 0%</b><br/> <b>Assigned 0%</b></p> |
| <p><b>Wishlist</b><br/>         Sell T-shirts on website<br/>         Arbor Press<br/>         Horizontal Band Saw<br/>         Compressed Air System</p>  |   |   |
| <p><b>Quadrotor</b><br/>         Make Wishlist of Parts<br/>         Fix the Quadrotor<br/>         Point Cloud Display<br/>         Design aluminum frame for Quad1<br/>         Make private repository<br/>         Email Harrison to Order Parts<br/>         USB to micro USB cable</p>                                 | <p><b>Quadrotor</b><br/> <br/> <b>Assigned 0%</b></p> |   |
| <p><b>RoboBuggy</b><br/>         Write a SURG Grant</p>  | <p><b>RoboBuggy</b><br/> <b>Assigned 40%</b></p>      |   |
| <p><b>RobOrchestra</b><br/>         Model Solenoids for brassbot in Solidworks<br/>         Get Pianobot modelled with the piano</p>   | <p><b>Assigned 0%</b><br/> <b>Assigned 0%</b></p>     |   |

Mechanica

Assigned

RobOr

Parts List (pianobot) (someone work on this? (...)

Algorithm for Pianobot?

**Tooltron**

Write tutorial about network programming

**Tooltron - 1.0**

script for network programming

notifications of tool boot packets in (...)

Put up a warning sign for Tooltron swiping (...)

Document the Network Bootloader

Document the States of the toolbox/cardbox

Server dies when internet is out

update server docs

**Tooltron - 1.1**

timeouts not working correctly

remove server hacks

organize repo

Document new Error codes on Cardbox

order more boards and replace drill-press (...)

**Tooltron - 2.0**

Keypad row 3 (7,8,9,C) does not work

MySQL Stored Procedures

Tooltron status indicator

**Underwater Swarm Bots**

FTDI cable

**WCTU**

WCTU - WCTU Version 1.0

Create v1.0 JS Client Revision 1

**Underwater Swarm Bots**

Assigned 0%

WCTU

WCTU -WCTU Version 1.0 50%

Assigned 0%