	2012-6			2012-7						20	012-8				2012-9				2	012-1	0			20	012-	11			
			24		5 26	27	28	29	30	31	3	32 3	33	34	35	36	37	38	39	40	41	42	4	3 44	1	45	46	47	
Colony		Co	ony	y																									
Battery Level Indicator																													
Improve library error codes																													
Better sanity check for invalid BOM type																													
XBee/Wireless Initialization																													
get all the library inti's and functions ()																													
Xbee Documentation																													
xbee baud rates																													
Wireless - core send, ack functions																													
Wireless - xbee.c																													
xbee id																													
investigate new AVR simulator?			_																										
Conclusion on filter design			-	ned																									
Figure out rangefinders group			-	ned																									
Complete SURG form		Assigned 0%																											
Check/Order robot battery clips		As	sigr	ned	50%																								
Line Follower Collimator																													
Redo robot pants																													
Get Colony videos onto VideoTron. Embed in ()																													
Clean up repository branches																													
Add Line Following to Library																													
Profile different mapping surfaces																													
Make Hunter-Prey Ref More Verbose																													
Clean up Colony-New and prepare for next ()																													
Implement Intersection Behavior																													
wl_basic_do_default(int *length) doesn't ()																													
Schedule Fleet Maintenence Day																													
Discuss and Contact about Extra Colony III ()																													

Colony - Hardware	
Design Dragonfly Replacement Board	
Investigate how to use the JTAG ICE	
Colony - Library	
Make sure all robots program the correct ()	
Colony - Reliability	
Automatically update robot status page ()	
Colony Scout	Colony Scout
Colony Environment	
Software Architecture	
<b>Reflow Oven Temperature Regulation</b>	
Update Boards on Eagle	
Research PCB Assemby Costing	
Website Work Log	
Video for Scout Intro	
Create ROS Node: Buttons	Assigned 100%
Create ROS Node: Timer	Assigned 100%
Create ROS Node: IMU	Assigned 0%
Create ROS Node: Accessory	Assigned 100%
Create ROS Node: Encoders	Assigned 100%
Create ROS Node: Wireless	Assigned 0%
Create ROS Node: USB Serial	Assigned 80%
Create ROS Node: Cliffsensors	Assigned 100%
Create ROS Node: BOM	Assigned 90%
Create ROS Node: Analog	Assigned 0%
BOM Interference Testing	Assigned 0%
BOM Driver Code	Assigned 0%
Sonar Wiring	Assigned 0%
Sonar Position Tracking	
Send Sonar Readings to ARM	
Automate Stepping and Sonar Reading	
Sonar on ARM	
Make ARM command Sonar on AVR	
Read IMU values and send to ARM	Assigned 0%

<b>D D U</b>	Assigned 0%
Pose Estimation	
Motor & Encoder Wiring	Assigned 10%
Control Motors (ARM)	
Track Encoders	
Charging Base	
Print and Test Scoutfly	
Create Scout Chassis	
Make wiring kits for Scout	
IMU on ARM	Assigned 0%
ROSSERIAL on ARM	Assigned 0%
CliffSensor on ARM	Assigned 0%
Create Transmitting Protocal	Assigned 0%
Wireless on ARM	Assigned 10%
Cliff Detection	Assigned 0%
Buttons on ARM	Assigned 0%
USB Serial on ARM	Assigned 0%
Control Headlights	
Power Up Rest of Scoutfly	
Get Old Boards and Funding Info	
Test AVR on ARM	Assigned 0%
Get Sonar Stepping and Reading	Assigned 0%
"Automated" Turning	Assigned 0%
Add Fuel Guage and Protection circuit ()	
BOM returns values even when IR LED ()	
File Error Service call	
Colony Scout - 1.0	
BOM Send/Receive Functions	
Assembly Instructions	
Fix Encoder pinout on breakfly	
Colony Scout - 1.2	
NanoRK Wireless Library	
Loook @ Robostix AVR<->ARM Comms ()	
Electronics Purchasing, OCT-08	Assigned 0%
Colony Scout - Development	
	I

System Wiring	
Look into accelerometer speed	
Email Red W	Assigned 0%
Create roboclub demo	Assigned 50%
Audio Command & Output Accessory	
Design SmartFly Smart Acessory ()	
Mechanical Work Log	Assigned 20%
Check speaker magnet interference ()	
НуLо	HyLo
type proposed proposal	Assigned 0%
Meeting	
Mechanical Logic Gates	Mechanical Logic Gates
Update - website	Assigned 0%
You Tube + Display Case	Assigned 0%
Website - host on roboclub	Assigned 0%
Look into getting copywrite	Assigned 0%
Wishlist	
Sell T-shirts on website	
Arbor Press	
Horizontal Band Saw	
Compressed Air System	
Quadrotor	Quadrotor
Make Wishlist of Parts	
Fix the Quadrotor	
Point Cloud Display	
Design aluminum frame for Quad1	Assigned 0%
Make private repository	
Email Harrison to Order Parts	
USB to micro USB cable	
RoboBuggy	RoboBuggy
Write a SURG Grant	Assigned 40%
RobOrchestra	
Model Solenoids for brassbot in Solidworks	Assigned 0%
Get Pianobot modelled with the piano	Assigned 0%

RobOrd

Parts List (pianobot) (someone work on this? ()	
Algorithm for Pianobot?	
Tooltron	
Write tutorial about network programming	
Tooltron - 1.0	
script for network programming	
notifications of tool boot packets in ()	
Put up a warning sign for Tooltron swiping ()	
Document the Network Bootloader	
Document the States of the toolbox/cardbox	
Server dies when internet is out	
update server docs	
Tooltron - 1.1	
timeouts not working correctly	
remove server hacks	
organize repo	
Document new Error codes on Cardbox	
order more boards and replace drill-press ()	
Tooltron - 2.0	
Keypad row 3 (7,8,9,C) does not work	
MySQL Stored Procedures	
Tooltron status indicator	
Underwater Swarm Bots	Underwater Swarm Bots
FTDI cable	Assigned 0%
wстu	
WCTU - WCTU Version 1.0	
Create v1.0 JS Client Revision 1	Assigned 0%

WCTU WCTU