	2013-4				2013-5				2013-6				2013-7				2013-8				2013-9			
	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39
Colony	**Colony**																									
Battery Level Indicator																										
Improve library error codes																										
Better sanity check for invalid BOM type																										
XBee/Wireless Initialization																										
get all the library inti's and functions (...)																										
Xbee Documentation																										
xbee baud rates																										
Wireless - core send, ack functions																										
Wireless - xbee.c																										
xbee id																										
Conclusion on filter design	Assigned 0%																									
Figure out rangefinders group	Assigned 0%																									
Complete SURG form	Assigned 0%																									
Check/Order robot battery clips	Assigned 50%																									
Line Follower Collimator																										
Redo robot pants																										
Get Colony videos onto VideoTron. Embed in (...)																										
Clean up repository branches																										
Add Line Following to Library																										
Profile different mapping surfaces																										
Make Hunter-Prey Ref More Verbose																										
Clean up Colony-New and prepare for next (...)																										
Implement Intersection Behavior																										
wl_basic_do_default(int *length) doesn't (...)																										
Schedule Fleet Maintenence Day																										
Discuss and Contact about Extra Colony III (...)																										
Colony - Hardware																										

Investigate how to use the JTAG ICE	
Colony - Library	
Make sure all robots program the correct (...)	**Colony Scout**
Colony Scout	
Colony Environment	
Software Architecture	
Reflow Oven Temperature Regulation	
Update Boards on Eagle	
Research PCB Assemby Costing	
Website Work Log	
Video for Scout Intro	
Create ROS Node: Buttons	**Assigned 100%**
Create ROS Node: Timer	**Assigned 100%**
Create ROS Node: IMU	**Assigned 0%**
Create ROS Node: Accessory	**Assigned 100%**
Create ROS Node: Encoders	**Assigned 100%**
Create ROS Node: Wireless	**Assigned 0%**
Create ROS Node: USB Serial	**Assigned 80%**
Create ROS Node: Cliffsensors	**Assigned 100%**
Create ROS Node: BOM	**Assigned 90%**
Create ROS Node: Analog	**Assigned 0%**
BOM Interference Testing	**Assigned 0%**
BOM Driver Code	**Assigned 0%**
Sonar Wiring	**Assigned 0%**
Sonar Position Tracking	
Send Sonar Readings to ARM	
Automate Stepping and Sonar Reading	
Sonar on ARM	
Make ARM command Sonar on AVR	
Read IMU values and send to ARM	**Assigned 0%**
Pose Estimation	**Assigned 0%**
Control Motors (ARM)	**Assigned 10%**
Track Encoders	
Charging Base	

Create Scout Chassis	
IMU on ARM	**Assigned 0%**
ROSSERIAL on ARM	**Assigned 0%**
CliffSensor on ARM	**Assigned 0%**
Create Transmitting Protocal	**Assigned 0%**
Wireless on ARM	**Assigned 10%**
Cliff Detection	**Assigned 0%**
Buttons on ARM	**Assigned 0%**
USB Serial on ARM	**Assigned 0%**
Power Up Rest of Scoutfly	
Get Old Boards and Funding Info	
Test AVR on ARM	**Assigned 0%**
Get Sonar Stepping and Reading	**Assigned 0%**
"Automated" Turning	**Assigned 0%**
Add Fuel Guage and Protection circuit (...)	
BOM returns values even when IR LED (...)	
File Error Service call	
Colony Scout - 1.0	
BOM Send/Receive Functions	
Assembly Instructions	
Fix Encoder pinout on breakfly	
Colony Scout - 1.2	
NanoRK Wireless Library	
Loook @ Robostix AVR<->ARM Comms (...)	
Electronics Purchasing, OCT-08	**Assigned 0%**
Colony Scout - Development	
System Wiring	
Look into accelerometer speed	
Email Red W	**Assigned 0%**
Create roboclub demo	**Assigned 50%**
Design SmartFly Smart Acessory (...)	
Mechanical Work Log	**Assigned 20%**
Check speaker magnet interference (...)	
HyLo	**HyLo**

type proposed proposal

Meeting

Mechanical Logic Gates

Update - website

You Tube + Display Case

Website - host on roboclub

Wishlist

Compressed Air System

Quadrotor

Fix the Quadrotor

Point Cloud Display

Design aluminum frame for Quad1

Make private repository

Email Harrison to Order Parts

USB to micro USB cable

RobOrchestra

Model Solenoids for brassbot in Solidworks

Get Pianobot modelled with the piano

Tooltron

Write tutorial about network programming

Tooltron - 1.0

script for network programming

notifications of tool boot packets in (...)

Document the Network Bootloader

Document the States of the toolbox/cardbox

Server dies when internet is out

update server docs

Tooltron - 1.1

timeouts not working correctly

remove server hacks

organize repo

Document new Error codes on Cardbox

order more boards and replace drill-press (...)

Tooltron - 2.0

Assigned 0%

Mechanical Logic Gates

Assigned 0%

Assigned 0%

Assigned 0%

Quadrotor

Assigned 0%

RobOrc

Assigned 0%

Assigned 0%

MySQL Stored Procedures
Underwater Swarm Bots
   FTDI cable
WCTU
   WCTU - WCTU Version 1.0
     Create v1.0 JS Client Revision 1
	Underwater Swarm Bots
	Assigned 0%
	WCTU
	WCTU -WCTU Version 1.0 50%
	Assigned 0%