	2017-3			2017-4					2017-5					2017-6					2017-7					2017-8					
			11	12	13	14	15	5 16	5 17	7 1	18	19	20	21	2	2	23	24	25	26	27	/ 2	8 29	) 3	30 3	31	32	33	34
Colony		Colo	ny				-						•	-						-	-								
Battery Level Indicator																													
Improve library error codes																													
Better sanity check for invalid BOM type																													
XBee/Wireless Initialization																													
get all the library inti's and functions ()																													
Xbee Documentation																													
xbee baud rates																													
Wireless - core send, ack functions																													
Wireless - xbee.c																													
xbee id																													
Conclusion on filter design		Assi	-																										
Figure out rangefinders group		Assi	-																										
Complete SURG form		Assi	-																										
Check/Order robot battery clips		Assi	gne	ed 50	%																								
Line Follower Collimator																													
Redo robot pants																													
Get Colony videos onto VideoTron. Embed in ()																													
Clean up repository branches																													
Add Line Following to Library																													
Profile different mapping surfaces																													
Make Hunter-Prey Ref More Verbose																													
Clean up Colony-New and prepare for next ()																													
Implement Intersection Behavior																													
wl_basic_do_default(int *length) doesn't ()																													
Schedule Fleet Maintenence Day																													
Discuss and Contact about Extra Colony III ()																													
Colony - Hardware																													

Investigate how to use the JTAG ICE	
Colony - Library	
Make sure all robots program the correct ()	
Colony Scout	Colony Scout
Colony Environment	
Software Architecture	
<b>Reflow Oven Temperature Regulation</b>	
Update Boards on Eagle	
Research PCB Assemby Costing	
Website Work Log	
Video for Scout Intro	
Create ROS Node: Buttons	Assigned 100%
Create ROS Node: Timer	Assigned 100%
Create ROS Node: IMU	Assigned 0%
Create ROS Node: Accessory	Assigned 100%
Create ROS Node: Encoders	Assigned 100%
Create ROS Node: Wireless	Assigned 0%
Create ROS Node: USB Serial	Assigned 80%
Create ROS Node: Cliffsensors	Assigned 100%
Create ROS Node: BOM	Assigned 90%
Create ROS Node: Analog	Assigned 0%
BOM Interference Testing	Assigned 0%
BOM Driver Code	Assigned 0%
Sonar Wiring	Assigned 0%
Sonar Position Tracking	
Send Sonar Readings to ARM	
Automate Stepping and Sonar Reading	
Sonar on ARM	
Make ARM command Sonar on AVR	
Read IMU values and send to ARM	Assigned 0%
Pose Estimation	Assigned 0%
Control Motors (ARM)	Assigned 10%
Track Encoders	
Charging Base	

Create Scout Chassis	
IMU on ARM	Assigned 0%
ROSSERIAL on ARM	Assigned 0%
CliffSensor on ARM	Assigned 0%
Create Transmitting Protocal	Assigned 0%
Wireless on ARM	Assigned 10%
Cliff Detection	Assigned 0%
Buttons on ARM	Assigned 0%
USB Serial on ARM	Assigned 0%
Power Up Rest of Scoutfly	
Get Old Boards and Funding Info	
Test AVR on ARM	Assigned 0%
Get Sonar Stepping and Reading	Assigned 0%
"Automated" Turning	Assigned 0%
Add Fuel Guage and Protection circuit ()	
BOM returns values even when IR LED ()	
File Error Service call	
Colony Scout - 1.0	
BOM Send/Receive Functions	
Assembly Instructions	
Fix Encoder pinout on breakfly	
Colony Scout - 1.2	
NanoRK Wireless Library	
Loook @ Robostix AVR<->ARM Comms ()	
Electronics Purchasing, OCT-08	Assigned 0%
Colony Scout - Development	
System Wiring	
Look into accelerometer speed	
Email Red W	Assigned 0%
Create roboclub demo	Assigned 50%
Design SmartFly Smart Acessory ()	
Mechanical Work Log	Assigned 20%
Check speaker magnet interference ()	
Lo	НуLо

· · ·	Assigned 0%
type proposed proposal	
Meeting	Mechanical Logic Gates
Mechanical Logic Gates	Assigned 0%
Update - website	Assigned 0%
You Tube + Display Case	Assigned 0%
Website - host on roboclub	
Wishlist	
Compressed Air System	Oundrates
Quadrotor	Quadrotor
Fix the Quadrotor	
Point Cloud Display	
Design aluminum frame for Quad1	Assigned 0%
Make private repository	
Email Harrison to Order Parts	
USB to micro USB cable	
RobOrchestra	RobOrchestra
Model Solenoids for brassbot in Solidworks	Assigned 0%
Get Pianobot modelled with the piano	Assigned 0%
Tooltron	
Write tutorial about network programming	
Tooltron - 1.0	
script for network programming	
notifications of tool boot packets in ()	
Document the Network Bootloader	
Document the States of the toolbox/cardbox	
Server dies when internet is out	
update server docs	
Tooltron - 1.1	
timeouts not working correctly	
remove server hacks	
organize repo	
Document new Error codes on Cardbox	
order more boards and replace drill-press ()	
Tooltron - 2.0	

MySQL Stored Procedures	
Underwater Swarm Bots	Underwater Swarm Bots
FTDI cable	Assigned 0%
WCTU	WCTU
WCTU - WCTU Version 1.0	WCTU -WCTU Version 1.0 50%
	Assigned 0%
Create v1.0 JS Client Revision 1	