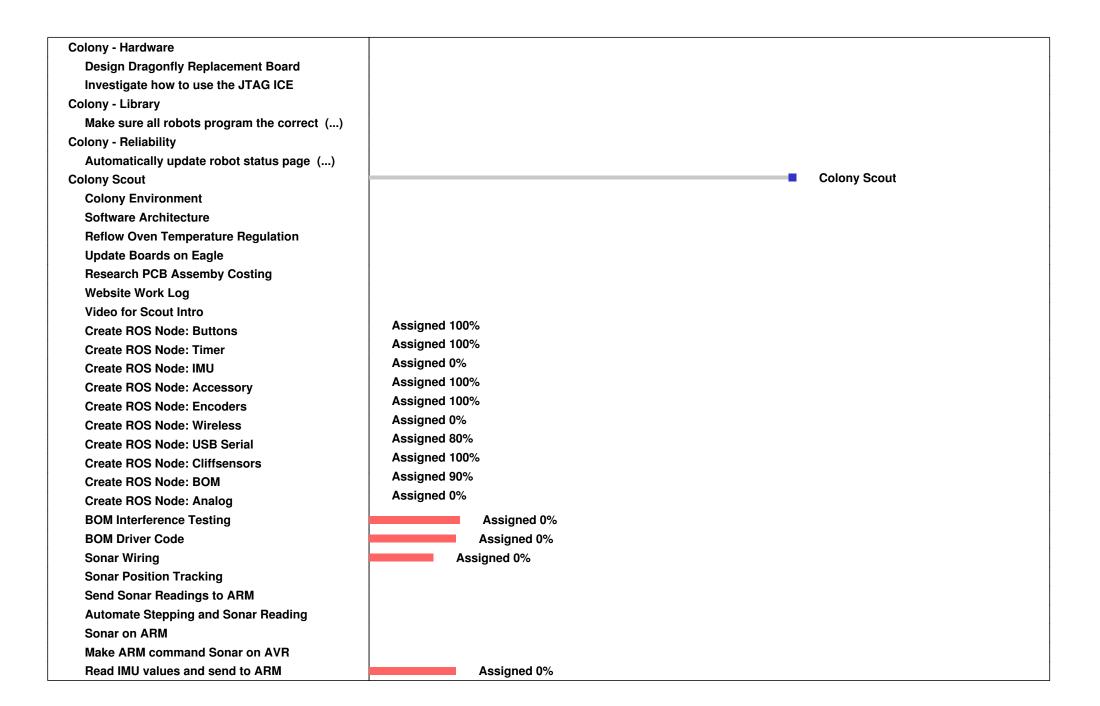
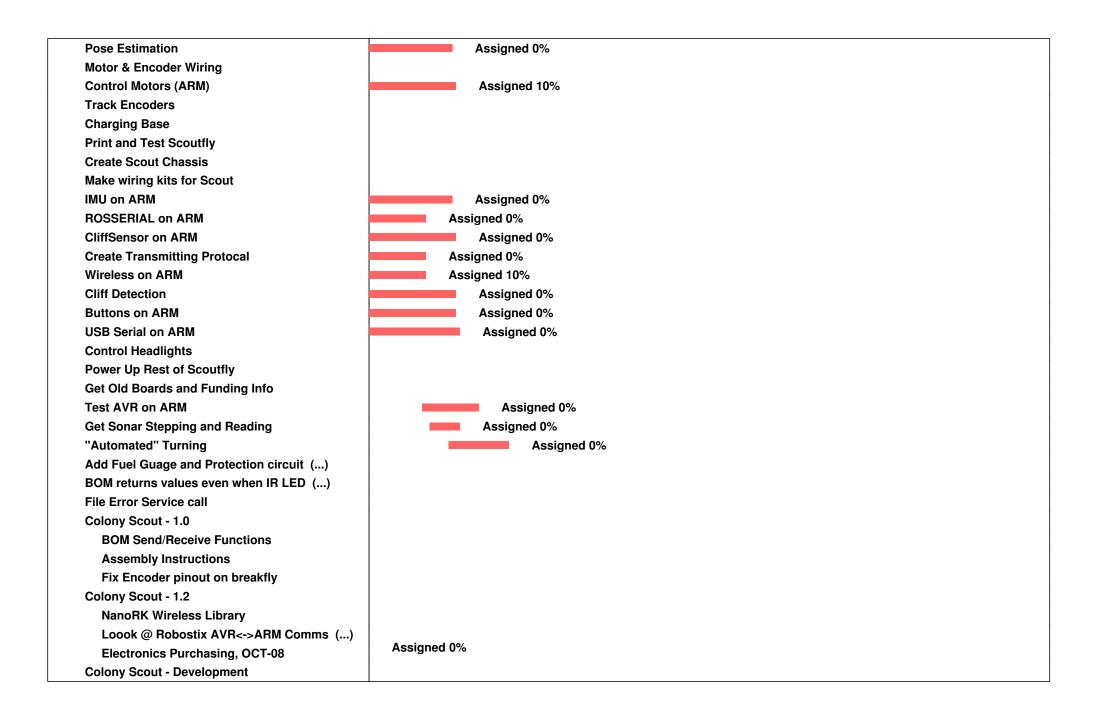
		2011-11			2011-12				2012-1					2012-2				2012-3					2012-4			
		45 4	6 47	48	8 49	50	51	52	1	2	3	4	5	6	7	8	9	) 1	10	11	12	13	14	15	16	17
Colony				-		-		•	•	•	•		-	•		•	•						Col	ony		•
Battery Level Indicator																										
Improve library error codes																										
Better sanity check for invalid BOM type																										
XBee/Wireless Initialization																										
get all the library inti's and functions ()																										
Xbee Documentation																										
xbee baud rates																										
Wireless - core send, ack functions																										
Wireless - xbee.c																										
xbee id																										
investigate new AVR simulator?																										
Conclusion on filter design		Assign																								
Figure out rangefinders group		Assign																								
Complete SURG form		Assign																								
Check/Order robot battery clips	4	Assign	ed 50°	%																						
Line Follower Collimator																										
Redo robot pants																										
Get Colony videos onto VideoTron. Embed in ()																										
Clean up repository branches																										
Add Line Following to Library																										
Profile different mapping surfaces																										
Make Hunter-Prey Ref More Verbose																										
Clean up Colony-New and prepare for next ()																										
Implement Intersection Behavior																										
wl_basic_do_default(int *length) doesn't ()																										
Schedule Fleet Maintenence Day																										
Discuss and Contact about Extra Colony III ()																										

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**System Wiring** Look into accelerometer speed Assigned 0% **Email Red W** Assigned 50% Create roboclub demo **Audio Command & Output Accessory** Design SmartFly Smart Acessory (...) Assigned 20% **Mechanical Work Log** Check speaker magnet interference (...) HyLo HyLo Assigned 0% type proposed proposal Meeting **Mechanical Logic Gates Mechanical Logic Gates** Assigned 0% Update - website Assigned 0% You Tube + Display Case Assigned 0% Website - host on roboclub Assigned 0% Look into getting copywrite Wishlist Sell T-shirts on website **Arbor Press Horizontal Band Saw Compressed Air System** Quadrotor Quadrotor Make Wishlist of Parts **Fix the Quadrotor Point Cloud Display** Design aluminum frame for Quad1 Assigned 0% Make private repository **Email Harrison to Order Parts** USB to micro USB cable RoboBuggy RoboBuggy Assigned 40% Write a SURG Grant RobOrchestra Assigned 0% Model Solenoids for brassbot in Solidworks Assigned 0% Get Pianobot modelled with the piano

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RobOrd

Parts List (pianobot) (someone work on this? (...) Algorithm for Pianobot? **Tooltron** Write tutorial about network programming Tooltron - 1.0 script for network programming notifications of tool boot packets in (...) Put up a warning sign for Tooltron swiping (...) **Document the Network Bootloader** Document the States of the toolbox/cardbox Server dies when internet is out update server docs Tooltron - 1.1 timeouts not working correctly remove server hacks organize repo **Document new Error codes on Cardbox** order more boards and replace drill-press (...) Tooltron - 2.0 Keypad row 3 (7,8,9,C) does not work **MySQL Stored Procedures Tooltron status indicator** Underwater Swarm Bots **Underwater Swarm Bots** FTDI cable Assigned 0% **WCTU** WCTU WCTU -WCTU Version 1.0 50% WCTU - WCTU Version 1.0 Assigned 0% Create v1.0 JS Client Revision 1

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