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| Pose Estimation | Assigned 0% |
| Motor & Encoder Wiring | |
| Control Motors (ARM) | Assigned 10% |
| Track Encoders | |
| Charging Base | |
| Print and Test Scoutfly | |
| Create Scout Chassis | |
| Make wiring kits for Scout | |
| IMU on ARM | Assigned 0% |
| ROSSERIAL on ARM | Assigned 0% |
| CliffSensor on ARM | Assigned 0% |
| Create Transmitting Protocol | Assigned 0% |
| Wireless on ARM | Assigned 10% |
| Cliff Detection | Assigned 0% |
| Buttons on ARM | Assigned 0% |
| USB Serial on ARM | Assigned 0% |
| Control Headlights | |
| Power Up Rest of Scoutfly | |
| Get Old Boards and Funding Info | |
| Test AVR on ARM | Assigned 0% |
| Get Sonar Stepping and Reading | Assigned 0% |
| "Automated" Turning | Assigned 0% |
| Add Fuel Gauge and Protection circuit (...) | |
| BOM returns values even when IR LED (...) | |
| File Error Service call | |
| Colony Scout - 1.0 | |
| BOM Send/Receive Functions | |
| Assembly Instructions | |
| Fix Encoder pinout on breakfly | |
| Colony Scout - 1.2 | |
| NanoRK Wireless Library | |
| Look @ Robostix AVR<->ARM Comms (...) | |
| Electronics Purchasing, OCT-08 | |
| Colony Scout - Development | Assigned 0% |

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|--------------------------------------------|------------------------------------|
| System Wiring | |
| Look into accelerometer speed | |
| Email Red W | Assigned 0% |
| Create roboclub demo | Assigned 50% |
| Audio Command & Output Accessory | |
| Design SmartFly Smart Accessory (...) | |
| Mechanical Work Log | Assigned 20% |
| Check speaker magnet interference (...) | |
| HyLo | HyLo |
| type proposed proposal | Assigned 0% |
| Meeting | |
| Mechanical Logic Gates | Mechanical Logic Gates |
| Update - website | Assigned 0% |
| You Tube + Display Case | Assigned 0% |
| Website - host on roboclub | Assigned 0% |
| Look into getting copywrite | Assigned 0% |
| Wishlist | |
| Sell T-shirts on website | |
| Arbor Press | |
| Horizontal Band Saw | |
| Compressed Air System | |
| Quadrotor | Quadrotor |
| Make Wishlist of Parts | |
| Fix the Quadrotor | |
| Point Cloud Display | |
| Design aluminum frame for Quad1 | Assigned 0% |
| Make private repository | |
| Email Harrison to Order Parts | |
| USB to micro USB cable | |
| RoboBuggy | RoboBuggy |
| Write a SURG Grant | Assigned 40% |
| RobOrchestra | |
| Model Solenoids for brassbot in Solidworks | <div><div></div></div> Assigned 0% |
| Get Pianobot modelled with the piano | <div><div></div></div> Assigned 0% |

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| <p>Parts List (pianobot) (someone work on this? (...)</p> <p>Algorithm for Pianobot?</p> <p>Tooltron</p> <p>Write tutorial about network programming</p> <p>Tooltron - 1.0</p> <ul style="list-style-type: none"> script for network programming notifications of tool boot packets in (...) Put up a warning sign for Tooltron swiping (...) Document the Network Bootloader Document the States of the toolbox/cardbox Server dies when internet is out update server docs <p>Tooltron - 1.1</p> <ul style="list-style-type: none"> timeouts not working correctly remove server hacks organize repo Document new Error codes on Cardbox order more boards and replace drill-press (...) <p>Tooltron - 2.0</p> <ul style="list-style-type: none"> Keypad row 3 (7,8,9,C) does not work MySQL Stored Procedures Tooltron status indicator <p>Underwater Swarm Bots</p> <p>FTDI cable</p> <p>WCTU</p> <p>WCTU - WCTU Version 1.0</p> <p>Create v1.0 JS Client Revision 1</p> | <p>Underwater Swarm Bots</p> <p>Assigned 0%</p> <p>WCTU</p> <p>WCTU -WCTU Version 1.0 50%</p> <p>Assigned 0%</p> |
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