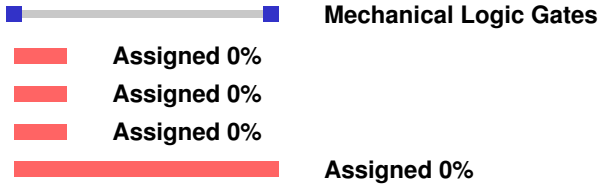
	2013-1				2013-2				2013-3				2013-4				2013-5					2013-6			
	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26
Colony	Colony																								
Battery Level Indicator																									
Improve library error codes																									
Better sanity check for invalid BOM type																									
XBee/Wireless Initialization																									
get all the library inti's and functions (...)																									
Xbee Documentation																									
xbee baud rates																									
Wireless - core send, ack functions																									
Wireless - xbee.c																									
xbee id																									
investigate new AVR simulator?																									
Conclusion on filter design	Assigned 0%																								
Figure out rangefinders group	Assigned 0%																								
Complete SURG form	Assigned 0%																								
Check/Order robot battery clips	Assigned 50%																								
Line Follower Collimator																									
Redo robot pants																									
Get Colony videos onto VideoTron. Embed in (...)																									
Clean up repository branches																									
Add Line Following to Library																									
Profile different mapping surfaces																									
Make Hunter-Prey Ref More Verbose																									
Clean up Colony-New and prepare for next (...)																									
Implement Intersection Behavior																									
wl_basic_do_default(int *length) doesn't (...)																									
Schedule Fleet Maintenence Day																									
Discuss and Contact about Extra Colony III (...)																									

Colony - Hardware	
Design Dragonfly Replacement Board	
Investigate how to use the JTAG ICE	
Colony - Library	
Make sure all robots program the correct (...)	
Colony - Reliability	
Automatically update robot status page (...)	
Colony Scout	**Colony Scout**
Colony Environment	
Software Architecture	
Reflow Oven Temperature Regulation	
Update Boards on Eagle	
Research PCB Assemby Costing	
Website Work Log	
Video for Scout Intro	
Create ROS Node: Buttons	**Assigned 100%**
Create ROS Node: Timer	**Assigned 100%**
Create ROS Node: IMU	**Assigned 0%**
Create ROS Node: Accessory	**Assigned 100%**
Create ROS Node: Encoders	**Assigned 100%**
Create ROS Node: Wireless	**Assigned 0%**
Create ROS Node: USB Serial	**Assigned 80%**
Create ROS Node: Cliffsensors	**Assigned 100%**
Create ROS Node: BOM	**Assigned 90%**
Create ROS Node: Analog	**Assigned 0%**
BOM Interference Testing	**Assigned 0%**
BOM Driver Code	**Assigned 0%**
Sonar Wiring	**Assigned 0%**
Sonar Position Tracking	
Send Sonar Readings to ARM	
Automate Stepping and Sonar Reading	
Sonar on ARM	
Make ARM command Sonar on AVR	
Read IMU values and send to ARM	**Assigned 0%**

Pose Estimation	Assigned 0%
Motor & Encoder Wiring	
Control Motors (ARM)	Assigned 10%
Track Encoders	
Charging Base	
Print and Test Scoutfly	
Create Scout Chassis	
Make wiring kits for Scout	
IMU on ARM	Assigned 0%
ROSSERIAL on ARM	Assigned 0%
CliffSensor on ARM	Assigned 0%
Create Transmitting Protocal	Assigned 0%
Wireless on ARM	Assigned 10%
Cliff Detection	Assigned 0%
Buttons on ARM	Assigned 0%
USB Serial on ARM	Assigned 0%
Control Headlights	
Power Up Rest of Scoutfly	
Get Old Boards and Funding Info	
Test AVR on ARM	Assigned 0%
Get Sonar Stepping and Reading	Assigned 0%
"Automated" Turning	Assigned 0%
Add Fuel Guage and Protection circuit (...)	
BOM returns values even when IR LED (...)	
File Error Service call	
Colony Scout - 1.0	
BOM Send/Receive Functions	
Assembly Instructions	
Fix Encoder pinout on breakfly	
Colony Scout - 1.2	
NanoRK Wireless Library	
Loook @ Robostix AVR<->ARM Comms (...)	
Electronics Purchasing, OCT-08	Assigned 0%
Colony Scout - Development	

System Wiring	
Look into accelerometer speed	
Email Red W	Assigned 0%
Create roboclub demo	Assigned 50%
Audio Command & Output Accessory	
Design SmartFly Smart Acessory (...)	
Mechanical Work Log	Assigned 20%
Check speaker magnet interference (...)	
HyLo	HyLo
type proposed proposal	Assigned 0%
Meeting	
Mechanical Logic Gates	 Mechanical Logic Gates
Update - website	Assigned 0%
You Tube + Display Case	Assigned 0%
Website - host on roboclub	Assigned 0%
Look into getting copywrite	Assigned 0%
Wishlist	
Sell T-shirts on website	
Arbor Press	
Horizontal Band Saw	
Compressed Air System	
Quadrotor	Quadrotor
Make Wishlist of Parts	
Fix the Quadrotor	
Point Cloud Display	
Design aluminum frame for Quad1	Assigned 0%
Make private repository	
Email Harrison to Order Parts	
USB to micro USB cable	
RoboBuggy	RoboBuggy
Write a SURG Grant	Assigned 40%
RobOrchestra	RobOrc
Model Solenoids for brassbot in Solidworks	Assigned 0%
Get Pianobot modelled with the piano	Assigned 0%

Parts List (pianobot) (someone work on this? (...)	
Algorithm for Pianobot?	
Tooltron	
Write tutorial about network programming	
Tooltron - 1.0	
script for network programming	
notifications of tool boot packets in (...)	
Put up a warning sign for Tooltron swiping (...)	
Document the Network Bootloader	
Document the States of the toolbox/cardbox	
Server dies when internet is out	
update server docs	
Tooltron - 1.1	
timeouts not working correctly	
remove server hacks	
organize repo	
Document new Error codes on Cardbox	
order more boards and replace drill-press (...)	
Tooltron - 2.0	
Keypad row 3 (7,8,9,C) does not work	
MySQL Stored Procedures	
Tooltron status indicator	
Underwater Swarm Bots	Underwater Swarm Bots
FTDI cable	Assigned 0%
WCTU	WCTU
WCTU - WCTU Version 1.0	WCTU -WCTU Version 1.0 50%
Create v1.0 JS Client Revision 1	Assigned 0%