

	2012-1				2012-2				2012-3				2012-4				2012-5				2012-6					
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26
Colony	<div><div></div></div>													Colony												
Battery Level Indicator																										
Improve library error codes																										
Better sanity check for invalid BOM type																										
XBee/Wireless Initialization																										
get all the library inti's and functions (...)																										
Xbee Documentation																										
xbee baud rates																										
Wireless - core send, ack functions																										
Wireless - xbee.c																										
xbee id																										
investigate new AVR simulator?																										
Conclusion on filter design	Assigned 0%																									
Figure out rangefinders group	Assigned 0%																									
Complete SURG form	Assigned 0%																									
Check/Order robot battery clips	Assigned 50%																									
Line Follower Collimator																										
Redo robot pants																										
Get Colony videos onto VideoTron. Embed in (...)																										
Clean up repository branches																										
Add Line Following to Library																										
Profile different mapping surfaces																										
Make Hunter-Prey Ref More Verbose																										
Clean up Colony-New and prepare for next (...)																										
Implement Intersection Behavior																										
wl_basic_do_default(int *length) doesn't (...)																										
Schedule Fleet Maintenance Day																										
Discuss and Contact about Extra Colony III (...)																										

<p>Colony - Hardware Design Dragonfly Replacement Board Investigate how to use the JTAG ICE</p> <p>Colony - Library Make sure all robots program the correct (...)</p> <p>Colony - Reliability Automatically update robot status page (...)</p> <p>Colony Scout Colony Environment Software Architecture Reflow Oven Temperature Regulation Update Boards on Eagle Research PCB Assembly Costing Website Work Log Video for Scout Intro Create ROS Node: Buttons Create ROS Node: Timer Create ROS Node: IMU Create ROS Node: Accessory Create ROS Node: Encoders Create ROS Node: Wireless Create ROS Node: USB Serial Create ROS Node: Cliffsensors Create ROS Node: BOM Create ROS Node: Analog BOM Interference Testing BOM Driver Code Sonar Wiring Sonar Position Tracking Send Sonar Readings to ARM Automate Stepping and Sonar Reading Sonar on ARM Make ARM command Sonar on AVR Read IMU values and send to ARM</p>	<div data-bbox="752 383 1153 406"></div> <div data-bbox="1196 383 1352 406">Colony Scout</div> <div data-bbox="797 678 976 1161"> Assigned 100% Assigned 100% Assigned 0% Assigned 100% Assigned 100% Assigned 0% Assigned 80% Assigned 100% Assigned 90% Assigned 0% Assigned 0% Assigned 0% Assigned 0% </div> <div data-bbox="797 1361 949 1385">Assigned 0%</div>
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Pose Estimation	Assigned 0%
Motor & Encoder Wiring	
Control Motors (ARM)	Assigned 10%
Track Encoders	
Charging Base	
Print and Test Scoutfly	
Create Scout Chassis	
Make wiring kits for Scout	
IMU on ARM	Assigned 0%
ROSSERIAL on ARM	Assigned 0%
CliffSensor on ARM	Assigned 0%
Create Transmitting Protocol	Assigned 0%
Wireless on ARM	Assigned 10%
Cliff Detection	Assigned 0%
Buttons on ARM	Assigned 0%
USB Serial on ARM	Assigned 0%
Control Headlights	
Power Up Rest of Scoutfly	
Get Old Boards and Funding Info	
Test AVR on ARM	Assigned 0%
Get Sonar Stepping and Reading	Assigned 0%
"Automated" Turning	Assigned 0%
Add Fuel Gauge and Protection circuit (...)	
BOM returns values even when IR LED (...)	
File Error Service call	
Colony Scout - 1.0	
BOM Send/Receive Functions	
Assembly Instructions	
Fix Encoder pinout on breakfly	
Colony Scout - 1.2	
NanoRK Wireless Library	
Look @ Robostix AVR<->ARM Comms (...)	
Electronics Purchasing, OCT-08	
Colony Scout - Development	Assigned 0%

System Wiring Look into accelerometer speed Email Red W Create roboclub demo Audio Command & Output Accessory Design SmartFly Smart Accessory (...) Mechanical Work Log Check speaker magnet interference (...)	
HyLo type proposed proposal Meeting	Assigned 0% Assigned 50%
Mechanical Logic Gates Update - website You Tube + Display Case Website - host on roboclub Look into getting copywrite	Assigned 20%
Wishlist Sell T-shirts on website Arbor Press Horizontal Band Saw Compressed Air System	
Quadrotor Make Wishlist of Parts Fix the Quadrotor Point Cloud Display Design aluminum frame for Quad1 Make private repository Email Harrison to Order Parts USB to micro USB cable	HyLo Assigned 0%
RoboBuggy Write a SURG Grant	Mechanical Logic Gates Assigned 0% Assigned 0% Assigned 0% Assigned 0%
RobOrchestra Model Solenoids for brassbot in Solidworks Get Pianobot modelled with the piano	Quadrotor Assigned 0%
	RoboBuggy Assigned 40%
	Assigned 0% Assigned 0%

RobOr

<p>Parts List (pianobot) (someone work on this? (...)</p> <p>Algorithm for Pianobot?</p> <p>Tooltron</p> <p>Write tutorial about network programming</p> <p>Tooltron - 1.0</p> <ul style="list-style-type: none"> script for network programming notifications of tool boot packets in (...) Put up a warning sign for Tooltron swiping (...) Document the Network Bootloader Document the States of the toolbox/cardbox Server dies when internet is out update server docs <p>Tooltron - 1.1</p> <ul style="list-style-type: none"> timeouts not working correctly remove server hacks organize repo Document new Error codes on Cardbox order more boards and replace drill-press (...) <p>Tooltron - 2.0</p> <ul style="list-style-type: none"> Keypad row 3 (7,8,9,C) does not work MySQL Stored Procedures Tooltron status indicator <p>Underwater Swarm Bots</p> <p>FTDI cable</p> <p>WCTU</p> <p>WCTU - WCTU Version 1.0</p> <p>Create v1.0 JS Client Revision 1</p>	<div> <div></div> <div>Underwater Swarm Bots</div> </div> <div> <div></div> <div>Assigned 0%</div> </div> <div> <div></div> <div>WCTU</div> </div> <div> <div></div> <div>WCTU -WCTU Version 1.0 50%</div> </div> <div> <div></div> <div>Assigned 0%</div> </div>
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