

Colony - Enhancement #228

Control algorithm for robots to move to an absolute position

02/04/2008 05:01 PM - Eugene Marinelli

Status: Wontfix	Start date:
Priority: Tabled	Due date:
Assignee:	% Done: 0%
Category: ColoNet	Estimated time: 0.00 hour
Target version: ColoNet	
Description Client will command a robot/robots to move to an absolute position. Robot will move while polling for its position, updating its movement based on the current error.	

History

#1 - 02/11/2008 06:10 PM - Eugene Marinelli

Coded, need to debug.

#2 - 02/12/2008 01:23 PM - Eugene Marinelli

Floating point and/or division causing robot to die.

#3 - 01/18/2009 11:17 PM - Eugene Marinelli

- Status changed from New to Assigned

#4 - 03/07/2009 11:41 PM - Kevin Woo

- Status changed from Assigned to New

- Assignee deleted (Unassigned Ticket -)

- Priority changed from Low to Tabled

#5 - 03/21/2009 12:53 PM - Rich Hong

- Category set to ColoNet

#6 - 09/30/2010 07:45 PM - John Sexton

- Status changed from New to Wontfix