

Issues

| # | Project | Tracker | Status | Priority | Subject | Assignee | Updated | Category | % Done |
|-----|---------|---------|----------|----------|-----------------------------|------------------|---------------------|-----------------------|--------|
| 329 | Colony | Task | Fixed | High | Program all robot's EEPROMs | Brad Neuman | 03/21/2009 12:49 PM | Hardware | 0 |
| 300 | Colony | Bug | Fixed | High | SPI failure | Brad Neuman | 03/21/2009 12:50 PM | Library | 0 |
| 299 | Colony | Bug | Invalid | High | SPI failure | Eugene Marinelli | 03/21/2009 12:50 PM | Library | 0 |
| 273 | Colony | Task | Fixed | Low | Bay Board I2C | Evan Mullinix | 03/21/2009 12:48 PM | Autonomous Recharging | 0 |
| 575 | Colony | Bug | Assigned | Tabled | Battery Level Indicator | John Sexton | 09/30/2010 08:00 PM | Library | 0 |
| 242 | Colony | Task | Fixed | Tabled | LCD module | Austin Buchan | 04/10/2009 05:04 PM | Hardware | 0 |
| 558 | Colony | Bug | Fixed | Urgent | USB Cables | Jimmy Bourne | 09/10/2009 04:52 PM | Hardware | 100 |
| 557 | Colony | Bug | Fixed | Urgent | Batteries | Jimmy Bourne | 09/10/2009 04:53 PM | Hardware | 100 |