

Issues

| # | Project | Tracker | Status | Priority | Subject | Assignee | Updated | Category | % Done |
|-----|---------|-------------|------------|----------|-----------------------------------|---------------|---------------------|-----------------------|--------|
| 350 | Colony | Task | Wontfix | Normal | Simulating Wireless | | 09/25/2010 03:16 PM | Simulator | 0 |
| 349 | Colony | Task | Wontfix | Tabled | Simulator Logging | | 09/30/2010 07:50 PM | Simulator | 0 |
| 348 | Colony | Task | Wontfix | Normal | Manage Robots through GUI | Siyuan Feng | 09/25/2010 03:15 PM | Simulator | 0 |
| 347 | Colony | Enhancement | Fixed | High | Deal with speed issues | Brad Neuman | 03/21/2009 12:51 PM | Simulator | 0 |
| 346 | Colony | Task | Fixed | Normal | Collisions with Obstacles | Ben Poole | 04/03/2009 05:10 PM | Simulator | 0 |
| 345 | Colony | Task | Wontfix | Normal | Circles in Environment | Nico Paris | 10/02/2010 07:25 PM | Simulator | 80 |
| 333 | Colony | Task | Fixed | High | Simulate Multiple Robots | Brad Neuman | 03/21/2009 12:51 PM | Simulator | 0 |
| 332 | Colony | Task | Wontfix | Normal | Environments | Nico Paris | 10/02/2010 07:11 PM | Simulator | 0 |
| 331 | Colony | Enhancement | Fixed | Normal | Cleanup on Closure | Brad Neuman | 03/21/2009 12:51 PM | Simulator | 0 |
| 328 | Colony | Task | Wontfix | Normal | Simulate Motors | | 10/02/2010 07:11 PM | Simulator | 0 |
| 327 | Colony | Task | Fixed | Low | Simulate Rangefinders | Nico Paris | 03/21/2009 12:51 PM | Simulator | 0 |
| 326 | Colony | Task | Wontfix | Normal | Display Robots in GUI | Siyuan Feng | 09/25/2010 03:14 PM | Simulator | 0 |
| 325 | Colony | Task | Fixed | High | Control Robot Processes | Brad Neuman | 03/21/2009 12:51 PM | Simulator | 0 |
| 324 | Colony | Task | Fixed | High | Share Motor Values with Simulator | Andrew Yeager | 03/21/2009 12:51 PM | Simulator | 0 |
| 238 | Colony | Task | Worksforme | Normal | Recharging Demo | Chris Mar | 03/21/2009 12:48 PM | Autonomous Recharging | 0 |