Colony

		201	3-8				20	13-9				201	3-1	0			20	13-	11			20	13-1	2			2	014	1	
	32			4 35	5	36	37	38	39	40	1 4	41	42	43	44	45	5 4	46	47	48	49	50	5	52	2 1	ı	2	3	4	
Colony	Со	lony	у .																	-										
Battery Level Indicator																														
Improve library error codes																														
Better sanity check for invalid BOM type																														
XBee/Wireless Initialization																														
get all the library inti's and functions ()																														
Xbee Documentation																														
xbee baud rates																														
Wireless - core send, ack functions																														
Wireless - xbee.c																														
xbee id																														
investigate new AVR simulator?																														
Conclusion on filter design		_		0%																										
Figure out rangefinders group		_		0%																										
Complete SURG form		_		0%																										
Check/Order robot battery clips	As	sigr	ned	50%																										
Line Follower Collimator																														
Redo robot pants																														
Get Colony videos onto VideoTron. Embed in ()																														
Clean up repository branches																														
Add Line Following to Library																														
Profile different mapping surfaces																														
Make Hunter-Prey Ref More Verbose																														
Clean up Colony-New and prepare for next ()																														
Implement Intersection Behavior																														
wl_basic_do_default(int *length) doesn't ()																														
Schedule Fleet Maintenence Day																														
Discuss and Contact about Extra Colony III ()																														

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Colony - Hardware
Design Dragonfly Replacement Board
Investigate how to use the JTAG ICE
Colony - Library
Make sure all robots program the correct ()
Colony - Reliability
Automatically update robot status page ()

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