	2012-6			2012-7					2012-8				2012-9					2012-10					2012-11			
	2	23 24	1 2	5 26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	
Colony		Color	ıy	•																						
Battery Level Indicator																										
Improve library error codes																										
Better sanity check for invalid BOM type																										
XBee/Wireless Initialization																										
get all the library inti's and functions ()																										
Xbee Documentation																										
xbee baud rates																										
Wireless - core send, ack functions																										
Wireless - xbee.c																										
xbee id																										
investigate new AVR simulator?																										
Conclusion on filter design		Assig																								
Figure out rangefinders group		Assig																								
Complete SURG form		Assig																								
Check/Order robot battery clips		Assig	ıned	50%																						
Line Follower Collimator																										
Redo robot pants																										
Get Colony videos onto VideoTron. Embed in ()																										
Clean up repository branches																										
Add Line Following to Library																										
Profile different mapping surfaces																										
Make Hunter-Prey Ref More Verbose																										
Clean up Colony-New and prepare for next ()																										
Implement Intersection Behavior																										
wl_basic_do_default(int *length) doesn't ()																										
Schedule Fleet Maintenence Day																										
Discuss and Contact about Extra Colony III ()																										

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Colony - Hardware **Design Dragonfly Replacement Board** Investigate how to use the JTAG ICE Colony - Reliability Automatically update robot status page (...) Colony - Library Make sure all robots program the correct (...) **Colony Scout Colony Scout Colony Environment Software Architecture Reflow Oven Temperature Regulation Update Boards on Eagle Research PCB Assemby Costing** Website Work Log Video for Scout Intro Assigned 100% **Create ROS Node: Buttons** Assigned 100% Create ROS Node: Timer Assigned 0% **Create ROS Node: IMU** Assigned 100% **Create ROS Node: Accessory** Assigned 100% **Create ROS Node: Encoders** Assigned 0% **Create ROS Node: Wireless** Assigned 80% Create ROS Node: USB Serial Assigned 100% Create ROS Node: Cliffsensors Assigned 90% **Create ROS Node: BOM** Assigned 0% Create ROS Node: Analog Assigned 0% **BOM Interference Testing** Assigned 0% **BOM Driver Code** Assigned 0% **Sonar Wiring** Assigned 0% **Get Sonar Stepping and Reading Sonar Position Tracking Send Sonar Readings to ARM Automate Stepping and Sonar Reading** Sonar on ARM Make ARM command Sonar on AVR

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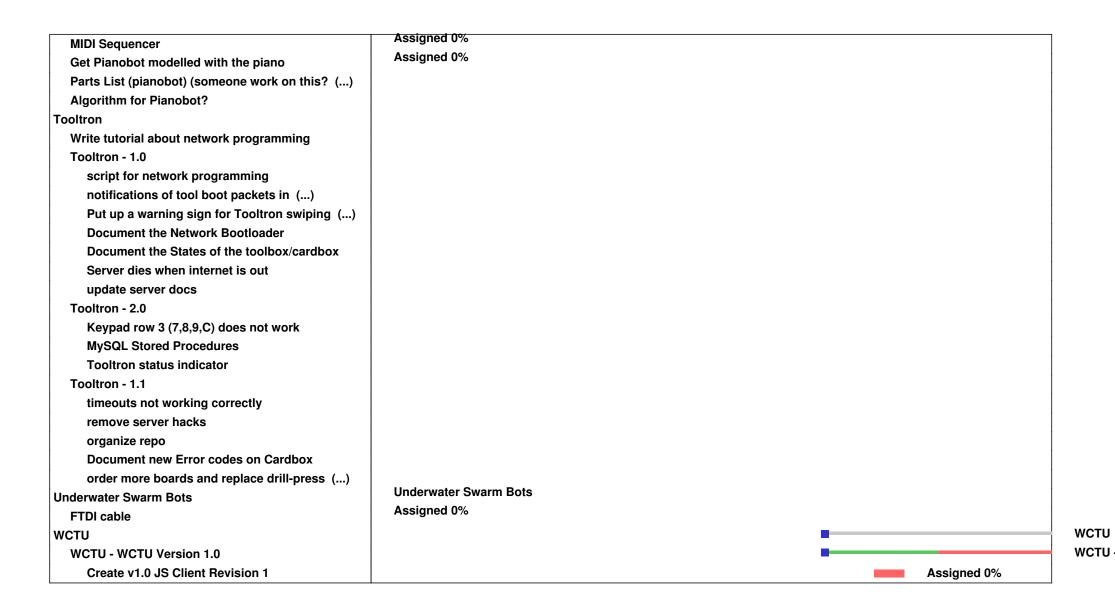
Read IMU values and send to ARM	Assigned 0%
Pose Estimation	Assigned 0%
Motor & Encoder Wiring	
Control Motors (ARM)	Assigned 10%
Track Encoders	
"Automated" Turning	Assigned 0%
Charging Base	
Print and Test Scoutfly	
Create Scout Chassis	
Make wiring kits for Scout	
IMU on ARM	Assigned 0%
ROSSERIAL on ARM	Assigned 0%
Test AVR on ARM	Assigned 0%
CliffSensor on ARM	Assigned 0%
Create Transmitting Protocal	Assigned 0%
Wireless on ARM	Assigned 10%
Cliff Detection	Assigned 0%
Buttons on ARM	Assigned 0%
USB Serial on ARM	Assigned 0%
Control Headlights	
Power Up Rest of Scoutfly	
Get Old Boards and Funding Info	
Add Fuel Guage and Protection circuit ()	
BOM returns values even when IR LED ()	
File Error Service call	
Colony Scout - Development	
System Wiring	
Look into accelerometer speed	
Email Red W	Assigned 0%
Create roboclub demo	Assigned 50%
<b>Audio Command &amp; Output Accessory</b>	
Design SmartFly Smart Acessory ()	
Mechanical Work Log	Assigned 20%
Check speaker magnet interference ()	

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Colony Scout - 1.0 **BOM Send/Receive Functions Assembly Instructions** Fix Encoder pinout on breakfly Colony Scout - 1.2 NanoRK Wireless Library Loook @ Robostix AVR<->ARM Comms (...) Assigned 0% **Electronics Purchasing, OCT-08** HyLo HyLo Assigned 0% type proposed proposal Meeting **Mechanical Logic Gates Mechanical Logic Gates** Assigned 0% Update - website Assigned 0% You Tube + Display Case Assigned 0% Website - host on roboclub Assigned 0% Look into getting copywrite Wishlist Sell T-shirts on website **Arbor Press Horizontal Band Saw Compressed Air System OPM Parking Meters Update Website Documentation** Improvements to Web Interface Quadrotor Quadrotor **Make Wishlist of Parts** Fix the Quadrotor **Point Cloud Display** Assigned 0% Design aluminum frame for Quad1 Make private repository **Email Harrison to Order Parts** USB to micro USB cable RobOrchestra Assigned 0% Model Solenoids for brassbot in Solidworks

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RobOrd



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