	2012-8			2012-9					2012-10					2012-11					2012-12					2013-1					
		32	33	34	35	36	3	7 38	39	4	0 4	41	42	43	44	45	5 4	6	47	48	49	5	0 5	1 5	52	1	2	3	4
Colony		Cold	ny	•	•	•	•		•		•	•	•			•	•	•				•	•	•			•		
Battery Level Indicator																													
Improve library error codes																													
Better sanity check for invalid BOM type																													
XBee/Wireless Initialization																													
get all the library inti's and functions ()																													
Xbee Documentation																													
xbee baud rates																													
Wireless - core send, ack functions																													
Wireless - xbee.c																													
xbee id																													
investigate new AVR simulator?																													
Conclusion on filter design		Ass	_																										
Figure out rangefinders group		Ass	-																										
Complete SURG form		Ass	-																										
Check/Order robot battery clips		Ass	gne	ed 50	%																								
Line Follower Collimator																													
Redo robot pants																													
Get Colony videos onto VideoTron. Embed in ()																													
Clean up repository branches																													
Add Line Following to Library																													
Profile different mapping surfaces																													
Make Hunter-Prey Ref More Verbose																													
Clean up Colony-New and prepare for next ()																													
Implement Intersection Behavior																													
wl_basic_do_default(int *length) doesn't ()																													
Schedule Fleet Maintenence Day																													
Discuss and Contact about Extra Colony III ()																													

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Colony - Hardware	
Design Dragonfly Replacement Board	
Investigate how to use the JTAG ICE	
Colony - Library	
Make sure all robots program the correct ()	
Colony - Reliability	
Automatically update robot status page ()	
Colony Scout	Colony Scout
Colony Environment	
Software Architecture	
Reflow Oven Temperature Regulation	
Update Boards on Eagle	
Research PCB Assemby Costing	
Website Work Log	
Video for Scout Intro	
Create ROS Node: Buttons	Assigned 100%
Create ROS Node: Timer	Assigned 100%
Create ROS Node: IMU	Assigned 0%
Create ROS Node: Accessory	Assigned 100%
Create ROS Node: Encoders	Assigned 100%
Create ROS Node: Wireless	Assigned 0%
Create ROS Node: USB Serial	Assigned 80%
Create ROS Node: Cliffsensors	Assigned 100%
Create ROS Node: BOM	Assigned 90%
Create ROS Node: Analog	Assigned 0%
BOM Interference Testing	Assigned 0%
BOM Driver Code	Assigned 0%
Sonar Wiring	Assigned 0%
Sonar Position Tracking	
Send Sonar Readings to ARM	
Automate Stepping and Sonar Reading	
Sonar on ARM	
Make ARM command Sonar on AVR	A
Read IMU values and send to ARM	Assigned 0%

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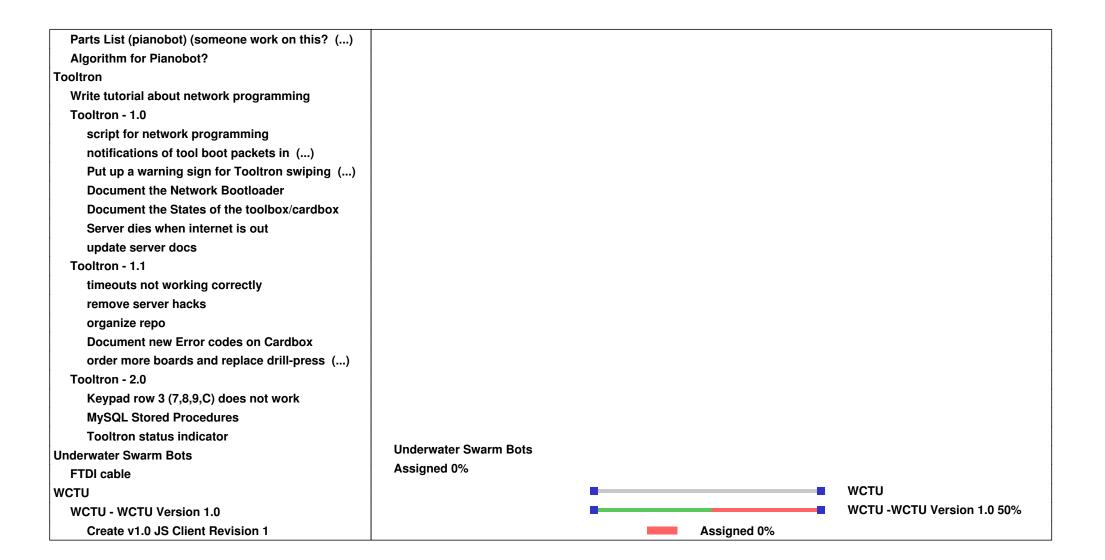
Pose Estimation	Assigned 0%
Motor & Encoder Wiring	
Control Motors (ARM)	Assigned 10%
Track Encoders	
Charging Base	
Print and Test Scoutfly	
Create Scout Chassis	
Make wiring kits for Scout	
IMU on ARM	Assigned 0%
ROSSERIAL on ARM	Assigned 0%
CliffSensor on ARM	Assigned 0%
Create Transmitting Protocal	Assigned 0%
Wireless on ARM	Assigned 10%
Cliff Detection	Assigned 0%
Buttons on ARM	Assigned 0%
USB Serial on ARM	Assigned 0%
Control Headlights	
Power Up Rest of Scoutfly	
Get Old Boards and Funding Info	
Test AVR on ARM	Assigned 0%
Get Sonar Stepping and Reading	Assigned 0%
"Automated" Turning	Assigned 0%
Add Fuel Guage and Protection circuit ()	
BOM returns values even when IR LED ()	
File Error Service call	
Colony Scout - 1.0	
BOM Send/Receive Functions	
Assembly Instructions	
Fix Encoder pinout on breakfly	
Colony Scout - 1.2	
NanoRK Wireless Library	
Loook @ Robostix AVR<>ARM Comms ()	
Electronics Purchasing, OCT-08	Assigned 0%
Colony Scout - Development	

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	·
System Wiring	
Look into accelerometer speed	A
Email Red W	Assigned 0%
Create roboclub demo	Assigned 50%
Audio Command & Output Accessory	
Design SmartFly Smart Acessory ()	
Mechanical Work Log	Assigned 20%
Check speaker magnet interference ()	
HyLo	HyLo
type proposed proposal	Assigned 0%
Meeting	
Mechanical Logic Gates	Mechanical Logic Gates
Update - website	Assigned 0%
You Tube + Display Case	Assigned 0%
Website - host on roboclub	Assigned 0%
Look into getting copywrite	Assigned 0%
Wishlist	
Sell T-shirts on website	
Arbor Press	
Horizontal Band Saw	
Compressed Air System	
Quadrotor	Quadrotor
Make Wishlist of Parts	
Fix the Quadrotor	
Point Cloud Display	
Design aluminum frame for Quad1	Assigned 0%
Make private repository	
Email Harrison to Order Parts	
USB to micro USB cable	
RoboBuggy	RoboBuggy
Write a SURG Grant	Assigned 40%
RobOrchestra	A
Model Solenoids for brassbot in Solidworks	Assigned 0%
Get Pianobot modelled with the piano	Assigned 0%

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RobOrd



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