	2013-4				2013-5					2013-6				2013-7				2013-8				2013-9				
	14			17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39
Colony		Colo	ıy		•	•		•		•	•			,	•			•	•	•	•	!				
Battery Level Indicator																										
Improve library error codes																										
Better sanity check for invalid BOM type																										
XBee/Wireless Initialization																										
get all the library inti's and functions ()																										
Xbee Documentation																										
xbee baud rates																										
Wireless - core send, ack functions																										
Wireless - xbee.c																										
xbee id																										
Conclusion on filter design		Assig																								
Figure out rangefinders group		Assi	-																							
Complete SURG form		Assi	-																							
Check/Order robot battery clips		Assig	gne	50% t	6																					
Line Follower Collimator																										
Redo robot pants																										
Get Colony videos onto VideoTron. Embed in ()																										
Clean up repository branches																										
Add Line Following to Library																										
Profile different mapping surfaces																										
Make Hunter-Prey Ref More Verbose																										
Clean up Colony-New and prepare for next ()																										
Implement Intersection Behavior																										
wl_basic_do_default(int *length) doesn't ()																										
Schedule Fleet Maintenence Day																										
Discuss and Contact about Extra Colony III ()																										
Colony - Hardware																										

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Investigate how to use the JTAG ICE	
Colony - Library	
Make sure all robots program the correct ()	
Colony Scout	Colony Scout
Colony Environment	
Software Architecture	
Reflow Oven Temperature Regulation	
Update Boards on Eagle	
Research PCB Assemby Costing	
Website Work Log	
Video for Scout Intro	
Create ROS Node: Buttons	Assigned 100%
Create ROS Node: Timer	Assigned 100%
Create ROS Node: IMU	Assigned 0%
Create ROS Node: Accessory	Assigned 100%
Create ROS Node: Encoders	Assigned 100%
Create ROS Node: Wireless	Assigned 0%
Create ROS Node: USB Serial	Assigned 80%
Create ROS Node: Cliffsensors	Assigned 100%
Create ROS Node: BOM	Assigned 90%
Create ROS Node: Analog	Assigned 0%
BOM Interference Testing	Assigned 0%
BOM Driver Code	Assigned 0%
Sonar Wiring	Assigned 0%
Sonar Position Tracking	
Send Sonar Readings to ARM	
Automate Stepping and Sonar Reading	
Sonar on ARM	
Make ARM command Sonar on AVR	
Read IMU values and send to ARM	Assigned 0%
Pose Estimation	Assigned 0%
Control Motors (ARM)	Assigned 10%
Track Encoders	
Charging Base	

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Create Scout Chassis	
IMU on ARM	Assigned 0%
ROSSERIAL on ARM	Assigned 0%
CliffSensor on ARM	Assigned 0%
Create Transmitting Protocal	Assigned 0%
Wireless on ARM	Assigned 10%
Cliff Detection	Assigned 0%
Buttons on ARM	Assigned 0%
USB Serial on ARM	Assigned 0%
Power Up Rest of Scoutfly	
Get Old Boards and Funding Info	
Test AVR on ARM	Assigned 0%
Get Sonar Stepping and Reading	Assigned 0%
"Automated" Turning	Assigned 0%
Add Fuel Guage and Protection circuit ()	
BOM returns values even when IR LED ()	
File Error Service call	
Colony Scout - 1.0	
BOM Send/Receive Functions	
Assembly Instructions	
Fix Encoder pinout on breakfly	
Colony Scout - 1.2	
NanoRK Wireless Library	
Loook @ Robostix AVR<->ARM Comms ()	
Electronics Purchasing, OCT-08	Assigned 0%
Colony Scout - Development	
System Wiring	
Look into accelerometer speed	
Email Red W	Assigned 0%
Create roboclub demo	Assigned 50%
Design SmartFly Smart Acessory ()	
Mechanical Work Log	Assigned 20%
Check speaker magnet interference ()	
0	HyLo

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	Assigned 0%	
type proposed proposal	i iooigii o ii	
Meeting	_	Machania II ania Oataa
Mechanical Logic Gates	Assigned 0%	Mechanical Logic Gates
Update - website	Assigned 0%	
You Tube + Display Case	Assigned 0%	
Website - host on roboclub	Assigned 0 /6	
Wishlist		
Compressed Air System	0	
Quadrotor	Quadrotor	
Fix the Quadrotor		
Point Cloud Display		
Design aluminum frame for Quad1	Assigned 0%	
Make private repository		
Email Harrison to Order Parts		
USB to micro USB cable		
RobOrchestra		
Model Solenoids for brassbot in Solidworks	Assigned 0%	
Get Pianobot modelled with the piano	Assigned 0%	
Tooltron		
Write tutorial about network programming		
Tooltron - 1.0		
script for network programming		
notifications of tool boot packets in ()		
Document the Network Bootloader		
Document the States of the toolbox/cardbox		
Server dies when internet is out		
update server docs		
Tooltron - 1.1		
timeouts not working correctly		
remove server hacks		
organize repo		
Document new Error codes on Cardbox		
order more boards and replace drill-press ()		
Tooltron - 2.0		

RobOrd

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MySQL Stored Procedures
Underwater Swarm Bots
FTDI cable
WCTU
WCTU - WCTU Version 1.0

Underwater Swarm Bots
Assigned 0%
WCTU
WCTU -WCTU Version 1.0 50%
Assigned 0%

CTU - WCTU Version 1.0
Create v1.0 JS Client Revision 1

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