



	2014-3				2014-4				2014-5				2014-6				2014-7				2014-8				
	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34
<b>Colony</b>	<b>Colony</b>																								
Battery Level Indicator																									
Improve library error codes																									
Better sanity check for invalid BOM type																									
XBee/Wireless Initialization																									
get all the library inti's and functions (...)																									
Xbee Documentation																									
xbee baud rates																									
Wireless - core send, ack functions																									
Wireless - xbee.c																									
xbee id																									
investigate new AVR simulator?																									
Conclusion on filter design	Assigned 0%																								
Figure out rangefinders group	Assigned 0%																								
Complete SURG form	Assigned 0%																								
Check/Order robot battery clips	Assigned 50%																								
Line Follower Collimator																									
Redo robot pants																									
Get Colony videos onto VideoTron. Embed in (...)																									
Clean up repository branches																									
Add Line Following to Library																									
Profile different mapping surfaces																									
Make Hunter-Prey Ref More Verbose																									
Clean up Colony-New and prepare for next (...)																									
Implement Intersection Behavior																									
wl_basic_do_default(int *length) doesn't (...)																									
Schedule Fleet Maintenance Day																									
Discuss and Contact about Extra Colony III (...)																									

<p><b>Colony - Hardware</b></p> <ul style="list-style-type: none"> <li>Design Dragonfly Replacement Board</li> <li>Investigate how to use the JTAG ICE</li> </ul> <p><b>Colony - Library</b></p> <ul style="list-style-type: none"> <li>Make sure all robots program the correct (...)</li> </ul> <p><b>Colony - Reliability</b></p> <ul style="list-style-type: none"> <li>Automatically update robot status page (...)</li> </ul> <p><b>Colony Scout</b></p> <ul style="list-style-type: none"> <li>Colony Environment</li> <li>Software Architecture</li> <li>Reflow Oven Temperature Regulation</li> <li>Update Boards on Eagle</li> <li>Research PCB Assembly Costing</li> <li>Website Work Log</li> <li>Video for Scout Intro</li> <li>Create ROS Node: Buttons</li> <li>Create ROS Node: Timer</li> <li>Create ROS Node: IMU</li> <li>Create ROS Node: Accessory</li> <li>Create ROS Node: Encoders</li> <li>Create ROS Node: Wireless</li> <li>Create ROS Node: USB Serial</li> <li>Create ROS Node: Cliff sensors</li> <li>Create ROS Node: BOM</li> <li>Create ROS Node: Analog</li> <li>BOM Interference Testing</li> <li>BOM Driver Code</li> <li>Sonar Wiring</li> <li>Sonar Position Tracking</li> <li>Send Sonar Readings to ARM</li> <li>Automate Stepping and Sonar Reading</li> <li>Sonar on ARM</li> <li>Make ARM command Sonar on AVR</li> <li>Read IMU values and send to ARM</li> </ul>	<p><b>Colony Scout</b></p> <p><b>Assigned 100%</b></p> <p><b>Assigned 100%</b></p> <p><b>Assigned 0%</b></p> <p><b>Assigned 100%</b></p> <p><b>Assigned 100%</b></p> <p><b>Assigned 0%</b></p> <p><b>Assigned 80%</b></p> <p><b>Assigned 100%</b></p> <p><b>Assigned 90%</b></p> <p><b>Assigned 0%</b></p> <p><b>Assigned 0%</b></p> <p><b>Assigned 0%</b></p> <p><b>Assigned 0%</b></p> <p><b>Assigned 0%</b></p>
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Pose Estimation	Assigned 0%
Motor & Encoder Wiring	
Control Motors (ARM)	Assigned 10%
Track Encoders	
Charging Base	
Print and Test Scoutfly	
Create Scout Chassis	
Make wiring kits for Scout	
IMU on ARM	Assigned 0%
ROSSERIAL on ARM	Assigned 0%
CliffSensor on ARM	Assigned 0%
Create Transmitting Protocol	Assigned 0%
Wireless on ARM	Assigned 10%
Cliff Detection	Assigned 0%
Buttons on ARM	Assigned 0%
USB Serial on ARM	Assigned 0%
Control Headlights	
Power Up Rest of Scoutfly	
Get Old Boards and Funding Info	
Test AVR on ARM	Assigned 0%
Get Sonar Stepping and Reading	Assigned 0%
"Automated" Turning	Assigned 0%
Add Fuel Guage and Protection circuit (...)	
BOM returns values even when IR LED (...)	
File Error Service call	
Colony Scout - 1.0	
BOM Send/Receive Functions	
Assembly Instructions	
Fix Encoder pinout on breakfly	
Colony Scout - 1.2	
NanoRK Wireless Library	
Look @ Robostix AVR<->ARM Comms (...)	
Electronics Purchasing, OCT-08	Assigned 0%
Colony Scout - Development	

<p><b>System Wiring</b></p> <ul style="list-style-type: none"> <li>Look into accelerometer speed</li> <li>Email Red W</li> <li>Create roboclub demo</li> <li>Audio Command &amp; Output Accessory</li> <li>Design SmartFly Smart Accessory (...)</li> <li>Mechanical Work Log</li> <li>Check speaker magnet interference (...)</li> </ul>	<p><b>Assigned 0%</b></p> <p><b>Assigned 50%</b></p>
<p><b>HyLo</b></p> <ul style="list-style-type: none"> <li>type proposed proposal</li> <li>Meeting</li> </ul>	<p><b>HyLo</b></p> <p><b>Assigned 0%</b></p>
<p><b>Mechanical Logic Gates</b></p> <ul style="list-style-type: none"> <li>Update - website</li> <li>You Tube + Display Case</li> <li>Website - host on roboclub</li> <li>Look into getting copywrite</li> </ul>	<p><b>Mechanical Logic Gates</b></p> <p><b>Assigned 0%</b></p> <p><b>Assigned 0%</b></p> <p><b>Assigned 0%</b></p> <p><b>Assigned 0%</b></p>
<p><b>Wishlist</b></p> <ul style="list-style-type: none"> <li>Sell T-shirts on website</li> <li>Arbor Press</li> <li>Horizontal Band Saw</li> <li>Compressed Air System</li> </ul>	
<p><b>Quadrotor</b></p> <ul style="list-style-type: none"> <li>Make Wishlist of Parts</li> <li>Fix the Quadrotor</li> <li>Point Cloud Display</li> <li>Design aluminum frame for Quad1</li> <li>Make private repository</li> <li>Email Harrison to Order Parts</li> <li>USB to micro USB cable</li> </ul>	<p><b>Quadrotor</b></p> <p><b>Assigned 0%</b></p>
<p><b>RoboBuggy</b></p> <ul style="list-style-type: none"> <li>Write a SURG Grant</li> </ul>	<p> <b>RoboBuggy</b></p> <p> <b>Assigned 40%</b></p>
<p><b>RobOrchestra</b></p> <ul style="list-style-type: none"> <li>Model Solenoids for brassbot in Solidworks</li> <li>Get Pianobot modelled with the piano</li> </ul>	<p><b>RobOrchestra</b></p> <p><b>Assigned 0%</b></p> <p><b>Assigned 0%</b></p>

<p>Parts List (pianobot) (someone work on this? (...))</p> <p>Algorithm for Pianobot?</p> <p>Tooltron</p> <p>Write tutorial about network programming</p> <p>Tooltron - 1.0</p> <ul style="list-style-type: none"> <li>script for network programming</li> <li>notifications of tool boot packets in (...)</li> <li>Put up a warning sign for Tooltron swiping (...)</li> <li>Document the Network Bootloader</li> <li>Document the States of the toolbox/cardbox</li> <li>Server dies when internet is out</li> <li>update server docs</li> </ul> <p>Tooltron - 1.1</p> <ul style="list-style-type: none"> <li>timeouts not working correctly</li> <li>remove server hacks</li> <li>organize repo</li> <li>Document new Error codes on Cardbox</li> <li>order more boards and replace drill-press (...)</li> </ul> <p>Tooltron - 2.0</p> <ul style="list-style-type: none"> <li>Keypad row 3 (7,8,9,C) does not work</li> <li>MySQL Stored Procedures</li> <li>Tooltron status indicator</li> </ul> <p>Underwater Swarm Bots</p> <ul style="list-style-type: none"> <li>FTDI cable</li> </ul> <p>WCTU</p> <ul style="list-style-type: none"> <li>WCTU - WCTU Version 1.0</li> <li>Create v1.0 JS Client Revision 1</li> </ul>	<p>Underwater Swarm Bots</p> <p>Assigned 0%</p> <p>WCTU</p> <p>WCTU -WCTU Version 1.0 50%</p> <p>Assigned 0%</p>
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