

	2014-3				2014-4				2014-5				2014-6				2014-7				2014-8				
	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34
Colony	Colony																								
Battery Level Indicator																									
Improve library error codes																									
Better sanity check for invalid BOM type																									
XBee/Wireless Initialization																									
get all the library inti's and functions (...)																									
Xbee Documentation																									
xbee baud rates																									
Wireless - core send, ack functions																									
Wireless - xbee.c																									
xbee id																									
Conclusion on filter design	Assigned 0%																								
Figure out rangefinders group	Assigned 0%																								
Complete SURG form	Assigned 0%																								
Check/Order robot battery clips	Assigned 50%																								
Line Follower Collimator																									
Redo robot pants																									
Get Colony videos onto VideoTron. Embed in (...)																									
Clean up repository branches																									
Add Line Following to Library																									
Profile different mapping surfaces																									
Make Hunter-Prey Ref More Verbose																									
Clean up Colony-New and prepare for next (...)																									
Implement Intersection Behavior																									
wl_basic_do_default(int *length) doesn't (...)																									
Schedule Fleet Maintenance Day																									
Discuss and Contact about Extra Colony III (...)																									
Colony - Hardware																									

<p>Investigate how to use the JTAG ICE</p> <p>Colony - Library</p> <p> Make sure all robots program the correct (...)</p> <p>Colony Scout</p> <p> Colony Environment</p> <p> Software Architecture</p> <p> Reflow Oven Temperature Regulation</p> <p> Update Boards on Eagle</p> <p> Research PCB Assembly Costing</p> <p> Website Work Log</p> <p> Video for Scout Intro</p> <p> Create ROS Node: Buttons</p> <p> Create ROS Node: Timer</p> <p> Create ROS Node: IMU</p> <p> Create ROS Node: Accessory</p> <p> Create ROS Node: Encoders</p> <p> Create ROS Node: Wireless</p> <p> Create ROS Node: USB Serial</p> <p> Create ROS Node: Cliffsensors</p> <p> Create ROS Node: BOM</p> <p> Create ROS Node: Analog</p> <p> BOM Interference Testing</p> <p> BOM Driver Code</p> <p> Sonar Wiring</p> <p> Sonar Position Tracking</p> <p> Send Sonar Readings to ARM</p> <p> Automate Stepping and Sonar Reading</p> <p> Sonar on ARM</p> <p> Make ARM command Sonar on AVR</p> <p> Read IMU values and send to ARM</p> <p> Pose Estimation</p> <p> Control Motors (ARM)</p> <p> Track Encoders</p> <p> Charging Base</p>	<p>Colony Scout</p> <p>Assigned 100%</p> <p>Assigned 100%</p> <p>Assigned 0%</p> <p>Assigned 100%</p> <p>Assigned 100%</p> <p>Assigned 0%</p> <p>Assigned 80%</p> <p>Assigned 100%</p> <p>Assigned 90%</p> <p>Assigned 0%</p> <p>Assigned 0%</p> <p>Assigned 0%</p> <p>Assigned 0%</p> <p>Assigned 0%</p> <p>Assigned 10%</p>
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Create Scout Chassis	Assigned 0%
IMU on ARM	Assigned 0%
ROSSERIAL on ARM	Assigned 0%
CliffSensor on ARM	Assigned 0%
Create Transmitting Protocol	Assigned 0%
Wireless on ARM	Assigned 10%
Cliff Detection	Assigned 0%
Buttons on ARM	Assigned 0%
USB Serial on ARM	Assigned 0%
Power Up Rest of Scoutfly	
Get Old Boards and Funding Info	
Test AVR on ARM	Assigned 0%
Get Sonar Stepping and Reading	Assigned 0%
"Automated" Turning	Assigned 0%
Add Fuel Guage and Protection circuit (...)	
BOM returns values even when IR LED (...)	
File Error Service call	
Colony Scout - 1.0	
BOM Send/Receive Functions	
Assembly Instructions	
Fix Encoder pinout on breakfly	
Colony Scout - 1.2	
NanoRK Wireless Library	
Look @ Robostix AVR<->ARM Comms (...)	
Electronics Purchasing, OCT-08	Assigned 0%
Colony Scout - Development	
System Wiring	
Look into accelerometer speed	
Email Red W	Assigned 0%
Create roboclub demo	Assigned 50%
Design SmartFly Smart Accessory (...)	
Mechanical Work Log	Assigned 20%
Check speaker magnet interference (...)	
HyLo	HyLo

<p>type proposed proposal</p> <p>Meeting</p> <p>Mechanical Logic Gates</p> <p>Update - website</p> <p>You Tube + Display Case</p> <p>Website - host on roboclub</p> <p>Wishlist</p> <p>Compressed Air System</p> <p>Quadrotor</p> <p>Fix the Quadrotor</p> <p>Point Cloud Display</p> <p>Design aluminum frame for Quad1</p> <p>Make private repository</p> <p>Email Harrison to Order Parts</p> <p>USB to micro USB cable</p> <p>RobOrchestra</p> <p>Model Solenoids for brassbot in Solidworks</p> <p>Get Pianobot modelled with the piano</p> <p>Tooltron</p> <p>Write tutorial about network programming</p> <p>Tooltron - 1.0</p> <p>script for network programming</p> <p>notifications of tool boot packets in (...)</p> <p>Document the Network Bootloader</p> <p>Document the States of the toolbox/cardbox</p> <p>Server dies when internet is out</p> <p>update server docs</p> <p>Tooltron - 1.1</p> <p>timeouts not working correctly</p> <p>remove server hacks</p> <p>organize repo</p> <p>Document new Error codes on Cardbox</p> <p>order more boards and replace drill-press (...)</p> <p>Tooltron - 2.0</p>	<p>Assigned 0%</p> <p>Mechanical Logic Gates</p> <p>Assigned 0%</p> <p>Assigned 0%</p> <p>Assigned 0%</p> <p>Quadrotor</p> <p>Assigned 0%</p> <p>RobOrchestra</p> <p>Assigned 0%</p> <p>Assigned 0%</p>
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MySQL Stored Procedures Underwater Swarm Bots FTDI cable WCTU WCTU - WCTU Version 1.0 Create v1.0 JS Client Revision 1	Underwater Swarm Bots Assigned 0% WCTU WCTU -WCTU Version 1.0 50% Assigned 0%
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