

	2013-11				2013-12				2014-1					2014-2				2014-3				2014-4					
	45	46	47	48	49	50	51	52	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17		
Colony	Colony																										
Battery Level Indicator																											
Improve library error codes																											
Better sanity check for invalid BOM type																											
XBee/Wireless Initialization																											
get all the library inti's and functions (...)																											
Xbee Documentation																											
xbee baud rates																											
Wireless - core send, ack functions																											
Wireless - xbee.c																											
xbee id																											
investigate new AVR simulator?																											
Conclusion on filter design	Assigned 0%																										
Figure out rangefinders group	Assigned 0%																										
Complete SURG form	Assigned 0%																										
Check/Order robot battery clips	Assigned 50%																										
Line Follower Collimator																											
Redo robot pants																											
Get Colony videos onto VideoTron. Embed in (...)																											
Clean up repository branches																											
Add Line Following to Library																											
Profile different mapping surfaces																											
Make Hunter-Prey Ref More Verbose																											
Clean up Colony-New and prepare for next (...)																											
Implement Intersection Behavior																											
wl_basic_do_default(int *length) doesn't (...)																											
Schedule Fleet Maintenance Day																											
Discuss and Contact about Extra Colony III (...)																											

<p>Colony - Hardware Design Dragonfly Replacement Board Investigate how to use the JTAG ICE</p> <p>Colony - Library Make sure all robots program the correct (...)</p> <p>Colony - Reliability Automatically update robot status page (...)</p> <p>Colony Scout Colony Environment Software Architecture Reflow Oven Temperature Regulation Update Boards on Eagle Research PCB Assembly Costing Website Work Log Video for Scout Intro Create ROS Node: Buttons Create ROS Node: Timer Create ROS Node: IMU Create ROS Node: Accessory Create ROS Node: Encoders Create ROS Node: Wireless Create ROS Node: USB Serial Create ROS Node: Cliffsensors Create ROS Node: BOM Create ROS Node: Analog BOM Interference Testing BOM Driver Code Sonar Wiring Sonar Position Tracking Send Sonar Readings to ARM Automate Stepping and Sonar Reading Sonar on ARM Make ARM command Sonar on AVR Read IMU values and send to ARM</p>	<p>Colony Scout</p> <p>Assigned 100% Assigned 100% Assigned 0% Assigned 100% Assigned 100% Assigned 0% Assigned 80% Assigned 100% Assigned 90% Assigned 0% Assigned 0% Assigned 0% Assigned 0%</p> <p>Assigned 0%</p>
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Pose Estimation	Assigned 0%
Motor & Encoder Wiring	
Control Motors (ARM)	Assigned 10%
Track Encoders	
Charging Base	
Print and Test Scoutfly	
Create Scout Chassis	
Make wiring kits for Scout	
IMU on ARM	Assigned 0%
ROSSERIAL on ARM	Assigned 0%
CliffSensor on ARM	Assigned 0%
Create Transmitting Protocol	Assigned 0%
Wireless on ARM	Assigned 10%
Cliff Detection	Assigned 0%
Buttons on ARM	Assigned 0%
USB Serial on ARM	Assigned 0%
Control Headlights	
Power Up Rest of Scoutfly	
Get Old Boards and Funding Info	
Test AVR on ARM	Assigned 0%
Get Sonar Stepping and Reading	Assigned 0%
"Automated" Turning	Assigned 0%
Add Fuel Guage and Protection circuit (...)	
BOM returns values even when IR LED (...)	
File Error Service call	
Colony Scout - 1.0	
BOM Send/Receive Functions	
Assembly Instructions	
Fix Encoder pinout on breakfly	
Colony Scout - 1.2	
NanoRK Wireless Library	
Look @ Robostix AVR<->ARM Comms (...)	
Electronics Purchasing, OCT-08	Assigned 0%
Colony Scout - Development	

<p>System Wiring</p> <ul style="list-style-type: none"> Look into accelerometer speed Email Red W Create roboclub demo Audio Command & Output Accessory Design SmartFly Smart Accessory (...) Mechanical Work Log Check speaker magnet interference (...) 	<p>Assigned 0%</p> <p>Assigned 50%</p>
<p>HyLo</p> <ul style="list-style-type: none"> type proposed proposal Meeting 	<p>HyLo</p> <p>Assigned 0%</p>
<p>Mechanical Logic Gates</p> <ul style="list-style-type: none"> Update - website You Tube + Display Case Website - host on roboclub Look into getting copywrite 	<p>Mechanical Logic Gates</p> <p>Assigned 0%</p> <p>Assigned 0%</p> <p>Assigned 0%</p> <p>Assigned 0%</p>
<p>Wishlist</p> <ul style="list-style-type: none"> Sell T-shirts on website Arbor Press Horizontal Band Saw Compressed Air System 	
<p>Quadrotor</p> <ul style="list-style-type: none"> Make Wishlist of Parts Fix the Quadrotor Point Cloud Display Design aluminum frame for Quad1 Make private repository Email Harrison to Order Parts USB to micro USB cable 	<p>Quadrotor</p> <p>Assigned 0%</p>
<p>RoboBuggy</p> <ul style="list-style-type: none"> Write a SURG Grant 	
<p>RobOrchestra</p> <ul style="list-style-type: none"> Model Solenoids for brassbot in Solidworks Get Pianobot modelled with the piano 	<p>RobOrchestra</p> <p>Assigned 0%</p> <p>Assigned 0%</p>

■ RoboBuggy
■ Assigned 40%

<p>Parts List (pianobot) (someone work on this? (...))</p> <p>Algorithm for Pianobot?</p> <p>Tooltron</p> <p>Write tutorial about network programming</p> <p>Tooltron - 1.0</p> <ul style="list-style-type: none"> script for network programming notifications of tool boot packets in (...) Put up a warning sign for Tooltron swiping (...) Document the Network Bootloader Document the States of the toolbox/cardbox Server dies when internet is out update server docs <p>Tooltron - 1.1</p> <ul style="list-style-type: none"> timeouts not working correctly remove server hacks organize repo Document new Error codes on Cardbox order more boards and replace drill-press (...) <p>Tooltron - 2.0</p> <ul style="list-style-type: none"> Keypad row 3 (7,8,9,C) does not work MySQL Stored Procedures Tooltron status indicator <p>Underwater Swarm Bots</p> <ul style="list-style-type: none"> FTDI cable <p>WCTU</p> <ul style="list-style-type: none"> WCTU - WCTU Version 1.0 Create v1.0 JS Client Revision 1 	<p>Underwater Swarm Bots</p> <p>Assigned 0%</p> <p>WCTU</p> <p>WCTU -WCTU Version 1.0 50%</p> <p>Assigned 0%</p>
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