

Colony - Enhancement #447

add debugging support in simulator

04/10/2009 06:39 PM - Brad Neuman

Status:	Wontfix	Start date:	04/10/2009
Priority:	Low	Due date:	
Assignee:	Brian Coltin	% Done:	0%
Category:	Simulator	Estimated time:	0.00 hour
Target version:			
Description the robot shared state should contain a file pointer to write all usb_put* output to. Currently it all goes to stdio, so there is no way to tell what comes from which robot. Another option which might be useful would be to add a robot id to the shared state and make the usb_put* function append "Robot #:" to all output or something like that.			

History

#1 - 09/25/2010 03:11 PM - John Sexton

- Status changed from Assigned to Wontfix